roc+0010

ROC

Slap Fingerprint Segmentation Evaluation III

Last Updated: 21 February 2025

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1 Participation Information

1.1 Names and Dates

- Organization Name: ROC
- SlapSeg III Identifier: roc+0010
- SlapSeg III API Version: 1.2.0
- Application Date: 29 January 2025
- First Submission Date: 29 January 2025 (as version 0008)
- Validation Date: 20 February 2025
- Completion Date: 21 February 2025

1.2 Libraries

Filename	MD5 Checksum	Size
libroc_fingerprint_representation.so	3cca0e4f7a33cd8d6a4886259ad8733b	98 MB
libroc_object_detection.so	4e3745d14c2d8049f0501410fb2c60ab	262 MB
libicutu.so.66	e52a996730797512d6bdbda16e38b111	220 kB
libroc_tattoo_representation.so.3.6	4e819a9b364e2a96807d6bc4f11ef7fa	83 MB
libroc_face_accurate_representation.so.3.6	2fa3671998db92f0e24a1d5eaad58a81	170 MB
libroc_face_balanced_representation.so	c3874691a833f5bbd6ad9c91cc53ffb7	34 MB
libroc_semantic_segmentation.so.3.6	ec34d851229a0c7e3852a2c8de4514ab	1 MB
libicuuc.so.66	847a1dc2d266d158449beb5b4229ba45	2 MB
libroc_latent_representation.so	cf90c53a54c33189910409fbffecd342	405 MB
libelft_roc_0014.so	5b3febbb1f8013ca557bea1ae0097659	143 kB
libicuio.so.66	d8b76e7ef55aa79a367725beeb1e82a9	60 kB
libroc_iris_representation.so	d64e6a8e8d9853b4c90c1d233dd3254d	58 MB
libQt5Concurrent.so.5.14	47ce700bc77c3e88816b4dc51327a65c	31 kB
libicudata.so.66	2236674edbe8efc94f2f681a6e373cdb	28 MB
libroc_latent_representation.so.3.6	cf90c53a54c33189910409fbffecd342	405 MB
libicui18n.so.66	053f6f9d58e59a75509e4bf5e2c21f96	3 MB
libroc_fingerprint_representation.so.3.6	3cca0e4f7a33cd8d6a4886259ad8733b	98 MB
libicutest.so.66	b5e76b46ddafa3671ac90bbe8fa8d240	82 kB
libQt5Core.so.5	56beb55e6c63caf0b622281eb7efca2e	7 MB
libroc_semantic_segmentation.so	ec34d851229a0c7e3852a2c8de4514ab	1 MB
libQt5Concurrent.so.5.14.2	47ce700bc77c3e88816b4dc51327a65c	31 kB
libroc_tattoo_representation.so	4e819a9b364e2a96807d6bc4f11ef7fa	83 MB
libpftiii_roc_0007.so	b853c3aa1c16f3325628cadec5b55212	39 kB
libroc.so.3.6	d3b2619c14d29b36c0edf42173ea0d7c	52 MB
libQt5Core.so	56beb55e6c63caf0b622281eb7efca2e	7 MB
libQt5Network.so.5	04318595fd24ee8a5c1b0d4eb5aee838	2 MB
libroc_face_balanced_representation.so.3.6	c3874691a833f5bbd6ad9c91cc53ffb7	34 MB
libroc_qbe_detection.so	909d80d3cde53db8608e5a9f1f2a1eb2	178 MB
libQt5Network.so.5.14	04318595fd24ee8a5c1b0d4eb5aee838	2 MB
libicutu.so.66.1	e52a996730797512d6bdbda16e38b111	220 kB
libroc_vehicle_detection.so	90c274be99a4d1f12e2dfd200011952c	140 MB
libicudata.so.66.1	2236674edbe8efc94f2f681a6e373cdb	28 MB
libQt5Network.so	04318595fd24ee8a5c1b0d4eb5aee838	2 MB
libroc_text_detection.so	825bba9bf64607748b601467c8cd6fee	128 MB
libQt5Core.so.5.14	56beb55e6c63caf0b622281eb7efca2e	7 MB
libroc_iris_representation.so.3.6	d64e6a8e8d9853b4c90c1d233dd3254d	58 MB
libQt5Core.so.5.14.2	56beb55e6c63caf0b622281eb7efca2e	7 MB
libQt5Concurrent.so.5	47ce700bc77c3e88816b4dc51327a65c	31 kB
libroc_object_detection.so.3.6	4e3745d14c2d8049f0501410fb2c60ab	262 MB
libicuuc.so.66.1	847a1dc2d266d158449beb5b4229ba45	2 MB
libicutest.so.66.1	b5e76b46ddafa3671ac90bbe8fa8d240	82 kB
libicui18n.so.66.1	053f6f9d58e59a75509e4bf5e2c21f96	3 MB
libroc_qbe_detection.so.3.6	909d80d3cde53db8608e5a9f1f2a1eb2	178 MB
libroc.so.3.6.0	d3b2619c14d29b36c0edf42173ea0d7c	52 MB
libroc_text_detection.so.3.6	825bba9bf64607748b601467c8cd6fee	128 MB
libQt5Network.so.5.14.2	04318595fd24ee8a5c1b0d4eb5aee838	2 MB
libroc.so	d3b2619c14d29b36c0edf42173ea0d7c	52 MB
libslapsegiii_roc_0010.so	43fe5cc24137733067a51041327fa9af	60 kB
libroc_face_accurate_representation.so	2fa3671998db92f0e24a1d5eaad58a81	170 MB
libroc_vehicle_detection.so.3.6	90c274be99a4d1f12e2dfd200011952c	140 MB
libicuio.so.66.1	d8b76e7ef55aa79a367725beeb1e82a9	60 kB
libQt5Concurrent.so	47ce700bc77c3e88816b4dc51327a65c	31 kB
libroc_fingerprint_representation.so	3cca0e4f7a33cd8d6a4886259ad8733b	98 MB
ROC.lic	7f6e51607c4c6a66492770d890eaab0c	588 B
libroc_fingerprint_representation.so.3.6	3cca0e4f7a33cd8d6a4886259ad8733b	98 MB

2 Tenprint Cards ("TwoInch" Data)

separated by slap orientation and capture technology.

2.1 Segmentation Timing

All algorithms are run over a small fixed corpus of TwoInch images to estimate the total runtime of the evaluation. To be evaluated under SlapSeg III, algorithms **must** segment the timing corpus, on average, in under 1 500 milliseconds. This maximum reference time is documented in the SlapSeg III test plan, and is subject to change. Times are measured by running a single process on an isolated compute node equipped with an Intel Gold 6254 CPU (submissions received prior to February 2022 were timed with a Intel Xeon E5-4650 CPU).*=

Box plots of segmentation times are separated by slap orientation and capture technology in Figure 1. Tabular representations are enumerated in Table 1. Results are reported in milliseconds.

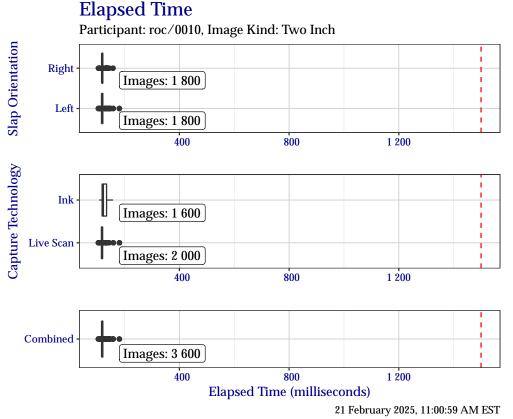


Figure 1: Box plots of elapsed time in milliseconds when segmenting the TwoInch timing test corpus,

Table 1: Elapsed time in milliseconds when segmenting the TwoInch timing test corpus, separated by slap orientation and capture technology.

	Right	Left	Live Scan	Ink	Combined
Minimum	105	105	105	108	105
25%	118	117	117	118	118
Median	119	118	118	121	118
75%	120	121	119	134	120
Maximum	158	181	181	158	181

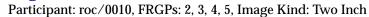
2.2 Segmentation Centers and Dimensions

2.2.1 Segmentation Centers

The plots in this section show the distribution of segmentation position centers (x, y) for TwoInch data. At the top of each figure is a combined plot for all finger positions of a given slap orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation centers for the right hand TwoInch data are shown in Figure 2 and plots of segmentation centers for the left hand are shown in Figure 3. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Centers have been normalized to 500 pixels per inch.

Points in each plot are plotted with a semi-transparent opacity. This results in points of particular color appearing "darker" to indicate a higher frequency of the observed value, while "lighter" points indicate a lower observed frequency.



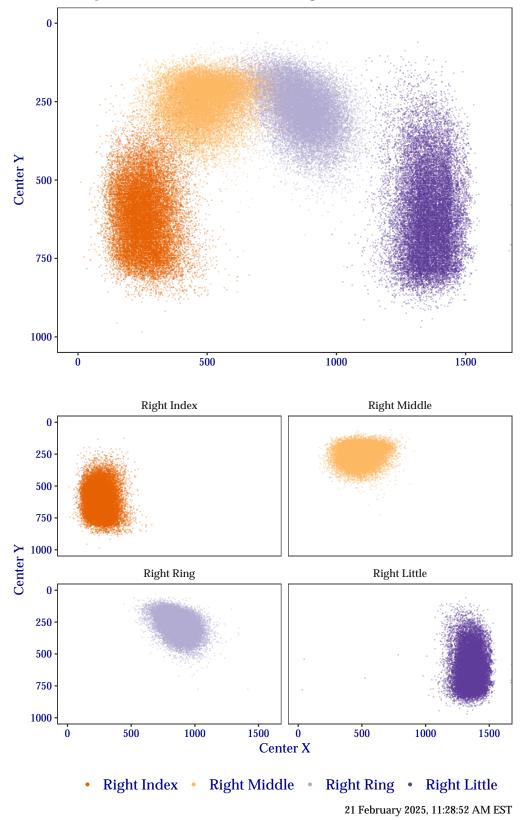


Figure 2: Segmentation centers for right hand TwoInch data.

Participant: roc/0010, FRGPs: 7, 8, 9, 10, Image Kind: Two Inch

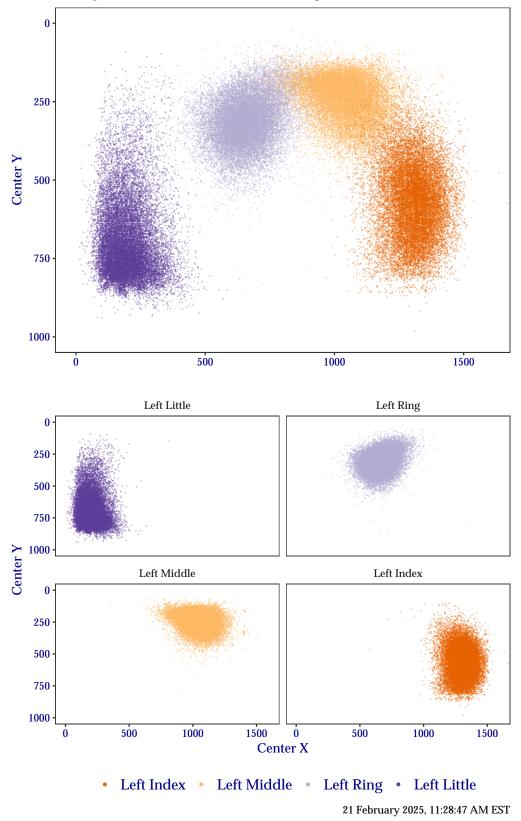


Figure 3: Segmentation centers for left hand TwoInch data.

2.2.2 Segmentation Dimensions

The plots in this section show the distribution of segmentation position widths and heights for TwoInch data. At the top of each figure is a combined plot for all finger positions of a given slap orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation position dimensions for the right hand TwoInch data are shown in Figure 4 and the left hand in Figure 5. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Dimensions have been normalized to 500 pixels per inch.

Segmentation Position Dimensions Participant: roc/0010, FRGPs: 2, 3, 4, 5, Image Kind: Two Inch

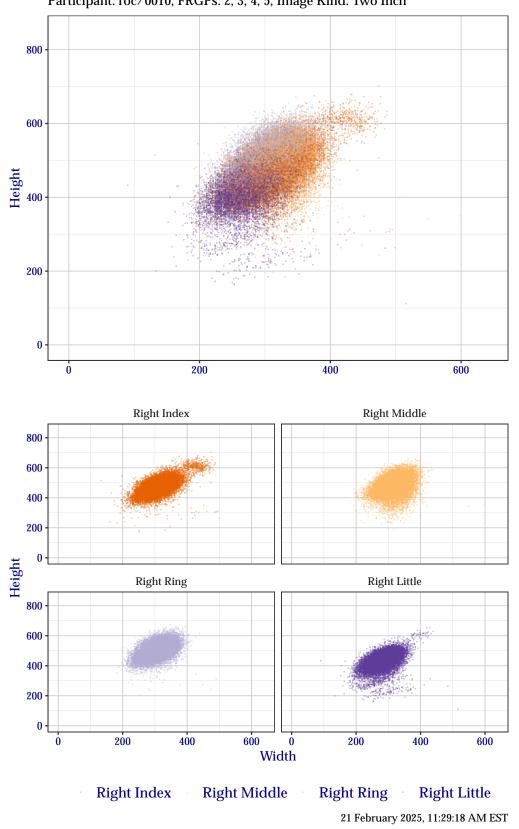


Figure 4: Segmentation position dimensions for right hand TwoInch data.

Participant: roc/0010, FRGPs: 7, 8, 9, 10, Image Kind: Two Inch 800 600 Height 400 200 0 200 400 600 Ö Left Little Left Ring 800 600 400 200 0 Height Left Middle Left Index 800 600 400 200 0 200 400 600 200 600 Ö Ö 400 Width Left Index Left Middle Left Ring Left Little

Segmentation Position Dimensions

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Figure 5: Segmentation position dimensions for left hand TwoInch data.

2.3 Detailed Segmentation Statistics

This section shows detailed results of segmentation of TwoInch data. Values in each table are the percentage that the variable in the left-most column was correctly segmented.

Each table has three columns of percentages. The *Standard Scoring* column shows the percentage of correctlysegmented positions based on the scoring metrics defined in the SlapSeg III scoring document. The *Ignoring Bottom Y* column shows how the percentage would change if the threshold for the *bottom Y* coordinate of the segmentation position was ignored. Similarly, the *Ignoring Bottom X* and *Y* columns shows how the percentage would change if only the top, left, and right sides of the segmentation position were considered. These two supplemental columns are included because it has traditionally been difficult to determine the exact location of the distal interphalangeal joint.

Table 2 shows how successful roc+0010 segmented fingers for each subject in the test corpus. Table 3 shows success for specific finger positions over the entire test corpus. Similarly, Table 4 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers on each slap image. Table 5 shows success for combinations of all fingers, Table 6 for just the index and middle fingers, and Table 7 for all except the little finger.

Table 2: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	99.8	99.8	99.8
2	99.7	99.7	99.8
3	99.5	99.5	99.6
4	98.8	98.9	99.0
5	95.1	95.1	95.2
6	94.6	94.7	95.0
7	93.2	93.6	94.2
8	82.9	86.0	87.7

Table 3: For all subjects, percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Index	96.2	97.4	98.4
Middle	98.5	98.9	99.0
Ring	98.4	98.7	98.8
Little	97.8	98.4	98.7
Left			
Index	97.6	98.0	98.2
Middle	97.9	98.2	98.4
Ring	97.7	98.2	98.5
Little	97.1	97.3	97.7

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Index			
Either	99.3	99.4	99.5
Both	90.2	91.5	92.7
Middle			
Either	99.5	99.5	99.6
Both	92.6	93.3	93.6
Ring			
Either	99.4	99.5	99.6
Both	92.4	93.2	93.7
Little			
Either	99.3	99.3	99.4
Both	90.9	91.6	92.3

Table 4: Percentage that a particular type of fingerprint was correctly segmented on *Either* or *Both* hands. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Table 5: Percentage of segmentation success by hand for combinations of all eight fingers of a TwoInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Any	99.7	99.7	99.7
At Least Two	99.6	99.6	99.7
At Least Three	99.1	99.2	99.5
All Four	92.6	94.8	96.0
Left			
Any	99.5	99.5	99.6
At Least Two	99.2	99.2	99.4
At Least Three	98.6	98.7	99.0
All Four	93.0	94.4	95.0

Table 6: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	99.5	99.5	99.6
Both Index and Middle	95.2	96.8	97.8
Left			
Either Index or Middle	99.3	99.3	99.4
Both Index and Middle	96.2	96.9	97.2

Table 7: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	99.7	99.7	99.7
At Least Two	99.3	99.4	99.6
All Three	94.1	95.9	97.0
Left			
Any	99.4	99.4	99.5
At Least Two	98.9	99.0	99.2
All Three	94.9	96.0	96.4

2.4 Handling Troublesome Images

2.4.1 Capture Failures

Segmentation algorithms may refuse to process an image. This may happen for a technical reason (e.g., the algorithm cannot parse the image data), or for a practical reason (e.g., the hand in the image is placed incorrectly). These failure scenarios are the result of capturing improper image data. In these types of scenarios, it is important to examine the cause of the failure. With many live scan capture setups, segmentation is performed immediately after capture. If an algorithm can detect that it won't be able to segment an image due to a technical or practical issue, it can alert the operator to perform a recapture before the subject leaves.

The SlapSeg III API encourages algorithms to identify these failure reasons by specifying pre-defined *deficiencies* in the image. Algorithms should attempt segmentation even if an image deficiency is encountered if at all possible. Note that SlapSeg III *guarantees* well-formed image data, so failures to parse are **not** an indicator of the data provided.

roc+0010 did **not** report any capture failures.

2.4.1.1 Recovery

When encountering a segmentation failure, SlapSeg III algorithms are encouraged to provide a *best-effort* segmentation when possible. In some cases, that best-effort may be correct, which reduces the amount of images that need to be manually adjudicated by an operator.

roc+0010 did not attempt any recovery segmentations.

2.4.2 Segmentation Failures

Even if an algorithm accepts an image for processing, it can still fail to process one or more fingers from the image, regardless of if the algorithm requested a recapture and provided best-effort segmentation.

The SlapSeg III API allows algorithms to communicate reasons for failure to process these fingers. In some cases, the distal phalanx in question might not be present in the image due to amputation or being placed outside the platen's capture area. It is imperative that the segmentation algorithm correctly report this as failing to segment the correct friction ridge generalized position without disrupting the sequence of valid positions present in the image. This can help prompt an operator to recapture or record additional information about the subject.

In SlapSeg III, a number of images are missing fingers or otherwise have fingers that will not be able to be segmented. Reasons for segmentation failures reported by roc+0010 are enumerated in Table 8.

Failure Reason	Fingers
Finger Not Found	266
Finger Found, but Can't Segment	0
Vendor Defined	0

Table 8: Count of self-reported segmentation failure reasoning.

2.4.3 Identifying Missing Fingers

A small portion of the test corpus in SlapSeg III are missing fingers. Table 9 shows how successful roc+0010 was in correctly determining if a finger was missing. The *Missed* row shows when a segmentation position was returned for a missing finger. All possible failure reasons are enumerated, but are not considered *Correctly Identified* because the algorithm specified failure for a reason other than the finger not being found.

Result	Percentage
Missed	40.6
Correctly Identified	59.4
Other Failure: Finger Found, but Can't Segment	0.0
Other Failure: Vendor Defined	0.0
Other Failure: Segmentation Not Attempted	0.0

Table 9: Performance of roc+0010 at detecting fingers missing from an image.

2.4.4 Sequence Error

Sequence error occurs when a fingerprint is segmented from an image but assigned an incorrect finger position (e.g., segmenting a right middle finger but labeling it a right index finger). Table 10 shows cases in which a segmentation position was returned that matched a ground truth segmentation position for a different finger in the same image.

Table 10: Percentage of images in the dataset where one or more segmentation positions correctly matched an incorrect finger position within the same image, indicating sequence error.

Hand	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Left	0.07	0.07	0.07
Right	0.02	0.02	0.02
Combined	0.04	0.04	0.04

2.5 Determining Orientation

An *optional* portion of the SlapSeg III API asked participants to determine the hand orientation of an image. Participants were provided the kind (e.g., Tenprint card) and capture technology (e.g., ink), and needed to determine whether the image was of the left or right hand.

Overall Two Inch accuracy: 99.9%

Table 11: Percentage of accuracy when determining hand orientation of a two inch image. The first column indicates the true hand orientation. Subsequent columns indicate the percentage of the time in which the indicated hand orientation was hypothesized.

	Left	Right	Skip
Left	99.9	0.1	0
Right	0.1	99.9	0

3 Identification Flats ("ThreeInch" Data)

3.1 Segmentation Timing

All algorithms are run over a small fixed corpus of ThreeInch images to estimate the total runtime of the evaluation. To be evaluated under SlapSeg III, algorithms **must** segment the timing corpus, on average, in under 1 500 milliseconds. This maximum reference time is documented in the SlapSeg III test plan, and is subject to change. Times are measured by running a single process on an isolated compute node equipped with an Intel Gold 6254 CPU (submissions received prior to February 2022 were timed with a Intel Xeon E5-4650 CPU).

Box plots of segmentation times are separated by hand in Figure 6, with tabular representations are enumerated in Table 12. Results are reported in milliseconds

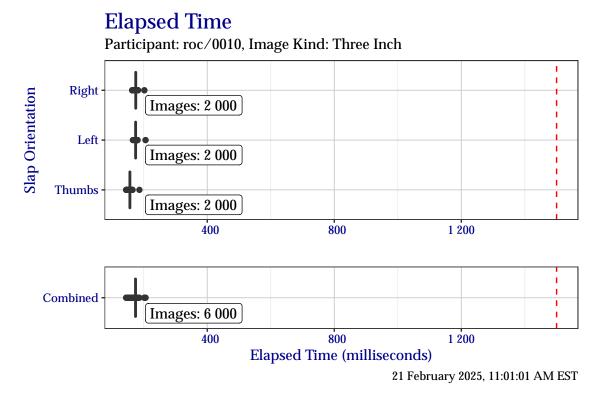


Figure 6: Box plots of elapsed time in milliseconds when segmenting the ThreeInch timing test corpus, separated by slap orientation.

Table 12: Elapsed time in milliseconds when segmenting the ThreeInch timing test corpus, separated by slap orientation.

	Right	Left	Thumbs	Combined
Minimum	164	166	144	144
25%	174	174	155	173
Median	175	174	156	174
75%	176	175	157	175
Maximum	202	206	186	206

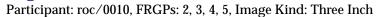
3.2 Segmentation Centers and Dimensions

3.2.1 Segmentation Centers

The plots in this section show the distribution of segmentation position centers (x, y) for ThreeInch data. At the top of each figure is a combined plot for all finger positions of a given hand orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation centers for the right hand ThreeInch data are shown in Figure 7, for the left hand in Figure 8, and for thumbs in Figure 9. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Centers have been normalized to 500 pixels per inch.

Points in each plot are plotted with a semi-transparent opacity. This results in points of particular color appearing "darker" to indicate a higher frequency of the observed value, while "lighter" points indicate a lower observed frequency.



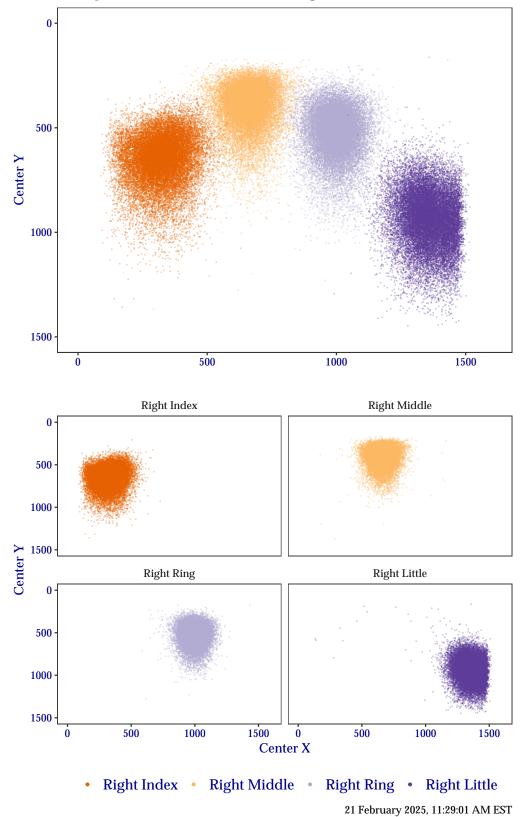
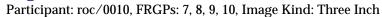
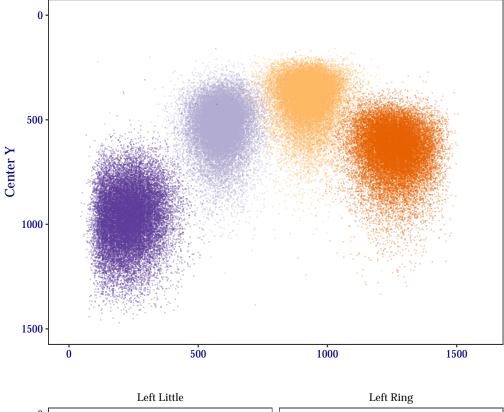


Figure 7: Segmentation centers for right hand ThreeInch data.





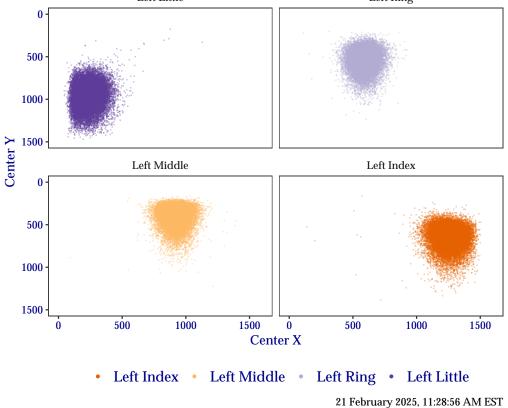
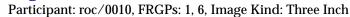
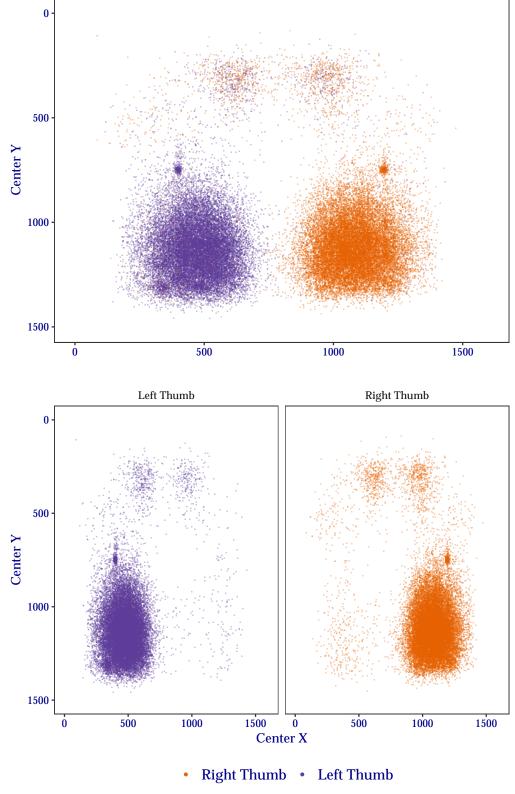


Figure 8: Segmentation centers for left hand ThreeInch data.





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Figure 9: Segmentation centers for thumb ThreeInch data.

3.2.2 Segmentation Dimensions

The plots in this section show the distribution of segmentation position widths and heights for ThreeInch data. At the top of each figure is a combined plot for all finger positions of a given hand orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation position dimensions for the right hand ThreeInch data are shown in Figure 11, for the left hand in Figure 10, and for thumbs in Figure 12. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Dimensions have been normalized to 500 pixels per inch.

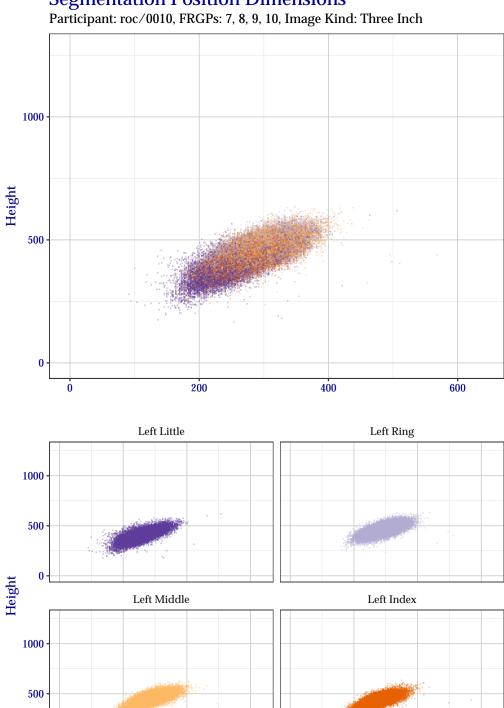
0

Ö

200

Left Index

400



Segmentation Position Dimensions

Figure 10: Segmentation position dimensions for left hand ThreeInch data.

600

Left Middle

Ö

Width

200

Left Ring

400

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Left Little

600

Height

Height

500

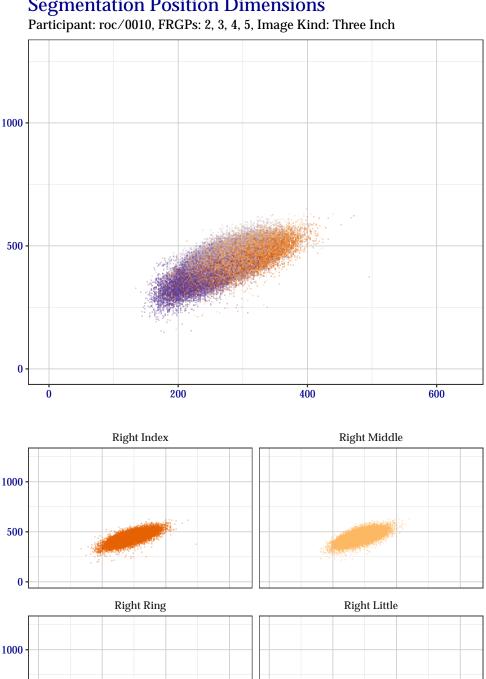
0

Ö

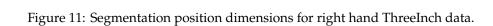
200

Right Index

400



Segmentation Position Dimensions



600

Right Middle

0

Width

200

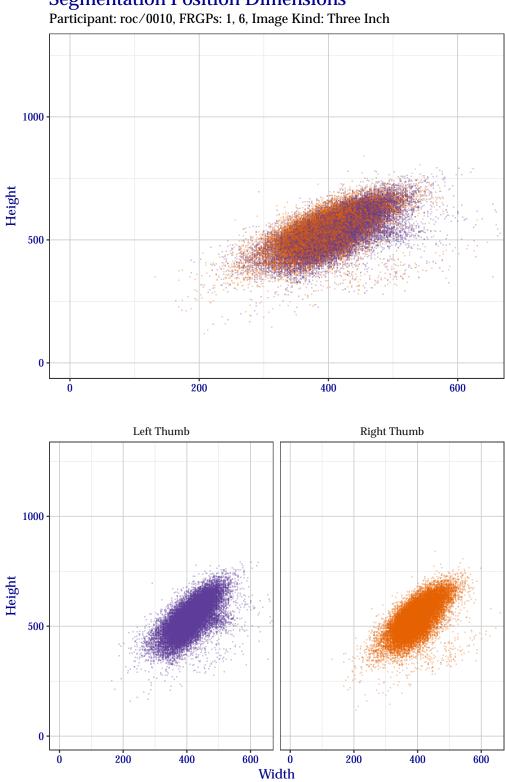
Right Ring

400

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600

Right Little



Segmentation Position Dimensions

Figure 12: Segmentation position dimensions for thumb ThreeInch data.

Right Thumb

Left Thumb

21 February 2025, 11:29:32 AM EST

3.3 Detailed Segmentation Statistics

This section shows detailed results of segmentation of ThreeInch data. Values in each table are the percentage that the variable in the left-most column was correctly segmented.

Each table has three columns of percentages. The *Standard Scoring* column shows the percentage of correctlysegmented positions based on the scoring metrics defined in the SlapSeg III scoring document. The *Ignoring Bottom Y* column shows how the percentage would change if the threshold for the *bottom Y* coordinate of the segmentation position was ignored. Similarly, the *Ignoring Bottom X and Y* columns shows how the percentage would change if only the top, left, and right sides of the segmentation position were considered. These two supplemental columns are included because it has traditionally been difficult to determine the exact location of the distal interphalangeal joint.

Table 13 shows how successful roc+0010 segmented fingers for each subject in the test corpus. Table 14 shows success for specific finger positions over the entire test corpus. Similarly, Table 15 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers on each slap image. Table 16 shows success for combinations of all fingers, Table 17 for just the index and middle fingers, and Table 18 for all except the little finger.

Table 13: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	99.9	99.9	99.9
2	99.6	99.6	99.7
3	98.5	98.5	98.5
4	98.2	98.2	98.2
5	95.9	95.9	95.9
6	95.9	95.9	95.9
7	95.8	95.8	95.9
8	95.5	95.5	95.5
9	91.0	91.2	91.5
10	79.1	79.7	81.1

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Thumb	90.3	90.4	90.9
Index	99.6	99.6	99.7
Middle	99.2	99.3	99.5
Ring	98.2	98.4	98.5
Little	98.0	98.0	98.1
Left			
Thumb	93.7	93.8	94.2
Index	98.8	98.8	98.9
Middle	99.3	99.3	99.5
Ring	99.4	99.5	99.7
Little	99.4	99.4	99.4

Table 14: For all subjects, percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Table 15: Percentage that a particular type of fingerprint was correctly segmented on *Either* or *Both* hands. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Thumb			
Either	96.3	96.3	96.4
Both	87.9	88.1	88.8
Index			
Either	99.9	99.9	99.9
Both	95.8	95.9	96.0
Middle			
Either	99.8	99.8	99.9
Both	96.0	96.0	96.5
Ring			
Either	99.8	99.9	99.9
Both	95.0	95.4	95.7
Little			
Either	99.7	99.7	99.7
Both	95.0	95.0	95.1

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Any	99.7	99.7	99.7
At Least Two	98.5	98.5	98.5
At Least Three	98.4	98.4	98.4
At Least Four	97.3	97.4	97.6
All Five	82.5	82.8	83.7
Left			
Any	99.8	99.8	99.9
At Least Two	98.5	98.5	98.5
At Least Three	98.4	98.4	98.4
At Least Four	97.8	97.9	98.0
All Five	86.8	87.1	87.8

Table 16: Percentage of segmentation success by hand for combinations of all ten fingers of a ThreeInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Table 17: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are gnored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either	99.9	99.9	99.9
Both	98.9	99.0	99.3
Left			
Either	99.9	99.9	99.9
Both	98.2	98.2	98.5

Table 18: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and right Y coordinates are ignored. *Ignoring Bottom X* and Y only checks the locations of the top left and right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	100.0	100.0	100.0
At Least Two	99.7	99.7	99.8
All Three	97.3	97.5	98.0
Left			
Any	100.0	100.0	100.0
At Least Two	99.8	99.8	99.8
All Three	97.7	97.9	98.3

3.4 Handling Troublesome Images

3.4.1 Capture Failures

Segmentation algorithms may refuse to process an image. This may happen for a technical reason (e.g., the algorithm cannot parse the image data), or for a practical reason (e.g., the hand in the image is placed incorrectly). These failure scenarios are the result of capturing improper image data. In these types of scenarios, it is important to examine the cause of the failure. With many live scan capture setups, segmentation is performed immediately after capture. If an algorithm can detect that it won't be able to segment an image due to a technical or practical issue, it can alert the operator to perform a recapture before the subject leaves.

The SlapSeg III API encourages algorithms to identify these failure reasons by specifying pre-defined *deficiencies* in the image. Algorithms should attempt segmentation even if an image deficiency is encountered if at all possible. Note that SlapSeg III *guarantees* well-formed image data, so failures to parse are **not** an indicator of the data provided.

roc+0010 did **not** report any capture failures.

3.4.1.1 Recovery

When encountering a segmentation failure, SlapSeg III algorithms are encouraged to provide a *best-effort* segmentation when possible. In some cases, that best-effort may be correct, which reduces the amount of images that need to be manually adjudicated by an operator.

roc+0010 did not attempt any recovery segmentations.

3.4.2 Segmentation Failures

Even if an algorithm accepts an image for processing, it can still fail to process one or more fingers from the image, regardless of if the algorithm requested a recapture and provided best-effort segmentation.

The SlapSeg III API allows algorithms to communicate reasons for failure to process these fingers. In some cases, the distal phalanx in question might not be present in the image due to amputation or being placed outside the platen's capture area. It is imperative that the segmentation algorithm correctly report this as failing to segment the correct friction ridge generalized position without disrupting the sequence of valid positions present in the image. This can help prompt an operator to recapture or record additional information about the subject.

In SlapSeg III, a number of images are missing fingers or otherwise have fingers that will not be able to be segmented. Reasons for segmentation failures reported by roc+0010 are enumerated in Table 19.

Failure Reason	Fingers
Finger Not Found	390
Finger Found, but Can't Segment	0
Vendor Defined	0

Table 19: Count of self-reported segmentation failure reasoning.

3.4.3 Identifying Missing Fingers

A small portion of the test corpus in SlapSeg III are missing fingers. Table 20 shows how successful roc+0010 was in correctly determining if a finger was missing. The *Missed* row shows when a segmentation position was returned for a missing finger. All possible failure reasons are enumerated, but are not considered *Correctly Identified* because the algorithm specified failure for a reason other than the finger not being found.

Result	Percentage
Missed	67.2
Correctly Identified	32.8
Other Failure: Finger Found, but Can't Segment	0.0
Other Failure: Vendor Defined	0.0
Other Failure: Segmentation Not Attempted	0.0

Table 20: Performance of roc+0010 at detecting fingers missing from an image.

3.4.4 Sequence Error

Sequence error occurs when a fingerprint is segmented from an image but assigned an incorrect finger position (e.g., segmenting a right middle finger but labeling it a right index finger). Table 21 shows cases in which a segmentation position was returned that matched a ground truth segmentation position for a different finger in the same image.

Table 21: Percentage of images in the dataset where one or more segmentation positions correctly matched an incorrect finger position within the same image, indicating sequence error.

Hand	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Left	0.14	0.15	0.15
Right	0.14	0.14	0.14
Thumbs	1.50	1.50	1.50
Combined	0.59	0.59	0.59

3.5 Determining Orientation

An *optional* portion of the SlapSeg III API asked participants to determine the hand orientation of an image. Participants were provided the kind (e.g., Identification Flat) and needed to determine whether the image was of the left hand, right hand, or thumbs.

Overall Three Inch accuracy: 96.8%

Table 22: Percentage of accuracy when determining hand orientation of a three inch image. The first column indicates the true hand orientation. Subsequent columns indicate the percentage of the time in which the indicated hand orientation was hypothesized.

	Left	Right	Skip	Thumbs
Left	99.8	0.2	0	0
Right	0.3	99.7	0	0
Thumbs	5.1	3.9	0.2	90.8

4 Upper Palm ("FiveInch" Data)

4.1 Segmentation Timing

All algorithms are run over a small fixed corpus of FiveInch images to estimate the total runtime of the evaluation. To be evaluated under SlapSeg III, algorithms **must** segment the timing corpus, on average, in under 1 500 milliseconds. This maximum reference time is documented in the SlapSeg III test plan, and is subject to change. Times are measured by running a single process on an isolated compute node equipped with an Intel Gold 6254 CPU (submissions received prior to February 2022 were timed with a Intel Xeon E5-4650 CPU).

Box plots of segmentation times are separated by slap orientation in Figure 13. Tabular representations are enumerated in Table 23. Results are reported in milliseconds.

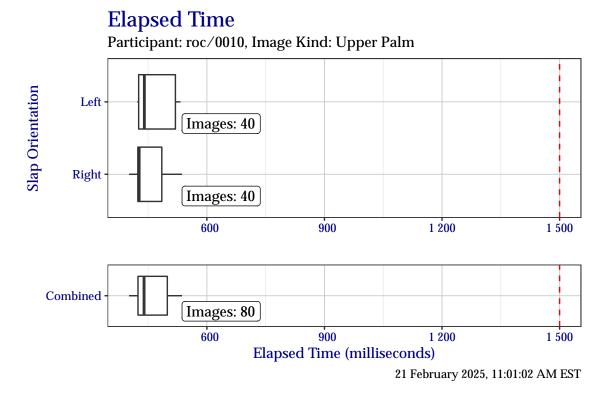


Figure 13: Box plots of elapsed time in milliseconds when segmenting the FiveInch timing test corpus, separated by slap orientation.

Table 23: Elapsed time in milliseconds when segmenting the FiveInch timing test corpus, separated by slap orientation.

	Right	Left	Combined
Minimum	401	422	401
25%	424	426	424
Median	427	440	440
75%	485	520	499
Maximum	537	533	537

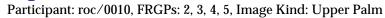
4.2 Segmentation Centers and Dimensions

4.2.1 Segmentation Centers

The plots in this section show the distribution of segmentation position centers (x, y) for FiveInch data. At the top of each figure is a combined plot for all finger positions of a given slap orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation centers for the right hand FiveInch data are shown in Figure 14 and plots of segmentation centers for the left hand are shown in Figure 15. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Centers have been normalized to 500 pixels per inch.

Points in each plot are plotted with a semi-transparent opacity. This results in points of particular color appearing "darker" to indicate a higher frequency of the observed value, while "lighter" points indicate a lower observed frequency.



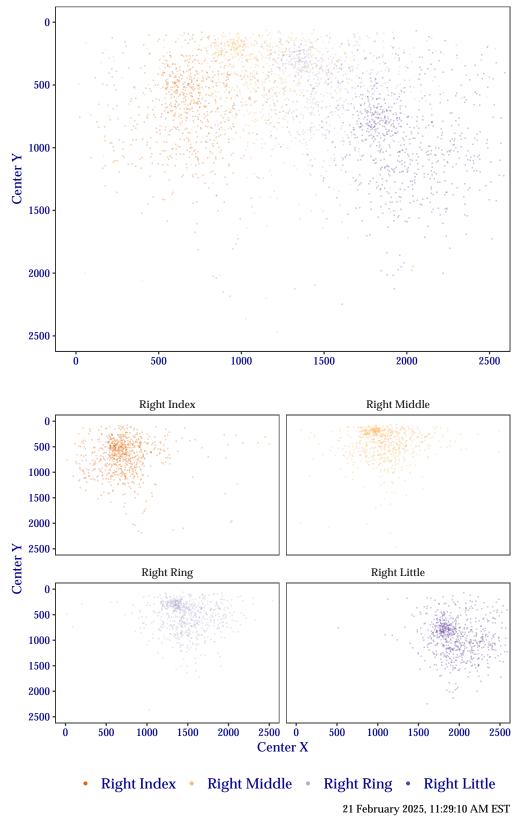


Figure 14: Segmentation centers for right hand FiveInch data.

Segmentation Position Centers

Participant: roc/0010, FRGPs: 7, 8, 9, 10, Image Kind: Upper Palm

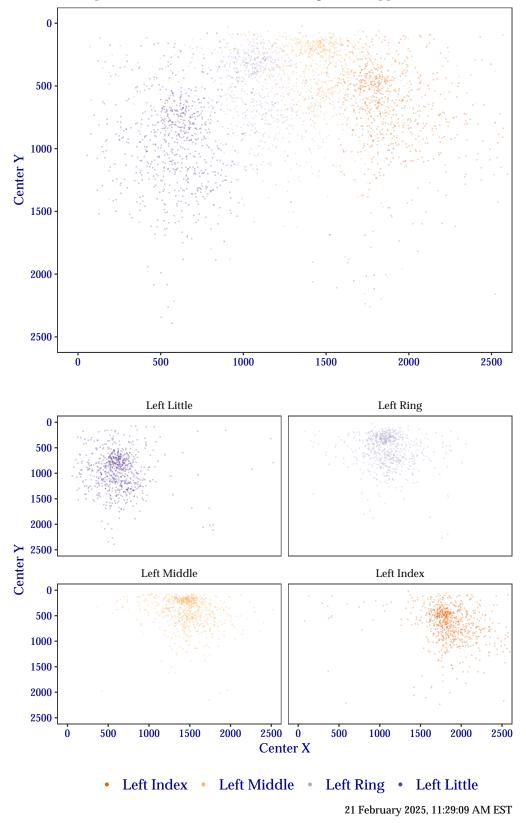
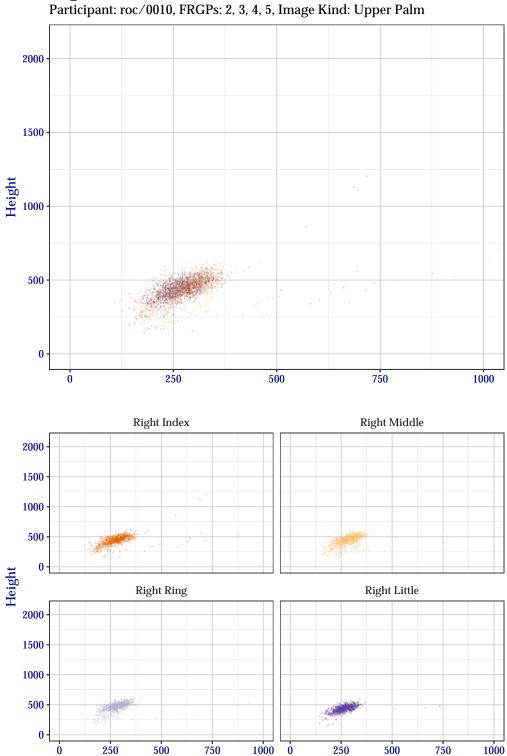


Figure 15: Segmentation centers for left hand FiveInch data.

4.2.2 Segmentation Dimensions

The plots in this section show the distribution of segmentation position widths and heights for FiveInch data. At the top of each figure is a combined plot for all finger positions of a given slap orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation position dimensions for the right hand FiveInch data are shown in Figure 16 and the left hand in Figure 17. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Dimensions have been normalized to 500 pixels per inch.



Segmentation Position Dimensions

Figure 16: Segmentation position dimensions for right hand FiveInch data.

Right Middle

Right Index

Width

Right Ring

Right Little

21 February 2025, 11:29:36 AM EST

1000

500

0

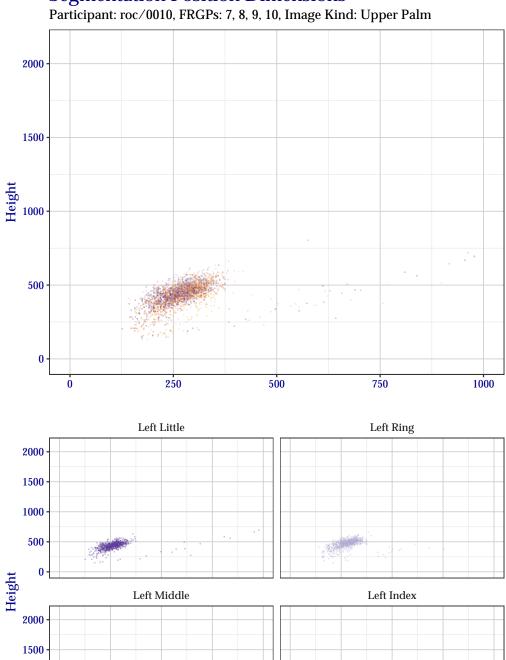
Ö

250

500

Left Index

750



Segmentation Position Dimensions

Figure 17: Segmentation position dimensions for left hand FiveInch data.

Left Middle

1000 0

Width

500

250

Left Ring

750

Left Little

21 February 2025, 11:29:35 AM EST

1000

4.3 Detailed Segmentation Statistics

This section shows detailed results of segmentation of FiveInch data. Values in each table are the percentage that the variable in the left-most column was correctly segmented.

Each table has three columns of percentages. The *Standard Scoring* column shows the percentage of correctlysegmented positions based on the scoring metrics defined in the SlapSeg III scoring document. The *Ignoring Bottom Y* column shows how the percentage would change if the threshold for the *bottom Y* coordinate of the segmentation position was ignored. Similarly, the *Ignoring Bottom X* and *Y* columns shows how the percentage would change if only the top, left, and right sides of the segmentation position were considered. These two supplemental columns are included because it has traditionally been difficult to determine the exact location of the distal interphalangeal joint.

Table 24 shows how successful roc+0010 segmented fingers for each subject in the test corpus. Table 25 shows success for specific finger positions over the entire test corpus. Similarly, Table 26 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers on each slap image. Table 27 shows success for combinations of all fingers, Table 28 for just the index and middle fingers, and Table 29 for all except the little finger.

Table 24: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	99.9	99.9	99.9
2	98.9	99.1	99.1
3	97.2	97.4	97.4
4	94.3	94.3	94.3
5	89.3	89.5	89.6
6	82.6	82.9	83.0
7	73.6	73.6	74.2
8	58.8	59.3	60.5

Table 25: For all subjects, percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Index	88.3	88.3	88.6
Middle	85.8	86.2	86.6
Ring	89.8	90.2	90.2
Little	91.9	91.9	91.9
Left			
Index	86.6	86.7	87.0
Middle	85.3	85.4	85.4
Ring	85.9	86.1	86.6
Little	86.7	86.7	87.3

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Index			
Either	94.6	94.6	94.6
Both	78.9	79.1	79.6
Middle			
Either	94.5	94.9	95.0
Both	75.2	75.4	75.6
Ring			
Either	95.7	95.8	95.8
Both	78.7	79.1	79.6
Little			
Either	97.6	97.6	97.8
Both	79.6	79.6	80.0

Table 26: Percentage that a particular type of fingerprint was correctly segmented on *Either* or *Both* hands. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Table 27: Percentage of segmentation success by hand for combinations of all eight fingers of a FiveInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Any	98.5	98.5	98.5
At Least Two	94.0	94.1	94.1
At Least Three	86.7	87.0	87.0
All Four	76.5	76.9	77.5
Left			
Any	98.5	98.5	98.7
At Least Two	93.1	93.1	93.1
At Least Three	83.0	83.2	83.6
All Four	69.9	70.2	71.0

Table 28: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	93.2	93.4	93.4
Both Index and Middle	80.9	81.1	81.8
Left			
Either Index or Middle	93.5	93.6	93.8
Both Index and Middle	78.4	78.5	78.6

Table 29: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	96.4	96.5	96.5
At Least Two	89.2	89.5	89.5
All Three	78.2	78.6	79.3
Left			
Any	96.0	96.0	96.2
At Least Two	86.6	86.7	86.9
All Three	75.2	75.5	76.0

4.4 Handling Troublesome Images

4.4.1 Capture Failures

Segmentation algorithms may refuse to process an image. This may happen for a technical reason (e.g., the algorithm cannot parse the image data), or for a practical reason (e.g., the hand in the image is placed incorrectly). These failure scenarios are the result of capturing improper image data. In these types of scenarios, it is important to examine the cause of the failure. With many live scan capture setups, segmentation is performed immediately after capture. If an algorithm can detect that it won't be able to segment an image due to a technical or practical issue, it can alert the operator to perform a recapture before the subject leaves.

The SlapSeg III API encourages algorithms to identify these failure reasons by specifying pre-defined *deficiencies* in the image. Algorithms should attempt segmentation even if an image deficiency is encountered if at all possible. Note that SlapSeg III *guarantees* well-formed image data, so failures to parse are **not** an indicator of the data provided.

roc+0010 did **not** report any capture failures.

4.4.1.1 Recovery

When encountering a segmentation failure, SlapSeg III algorithms are encouraged to provide a *best-effort* segmentation when possible. In some cases, that best-effort may be correct, which reduces the amount of images that need to be manually adjudicated by an operator.

roc+0010 did not attempt any recovery segmentations.

4.4.2 Segmentation Failures

Even if an algorithm accepts an image for processing, it can still fail to process one or more fingers from the image, regardless of if the algorithm requested a recapture and provided best-effort segmentation.

The SlapSeg III API allows algorithms to communicate reasons for failure to process these fingers. In some cases, the distal phalanx in question might not be present in the image due to amputation or being placed outside the platen's capture area. It is imperative that the segmentation algorithm correctly report this as failing to segment the correct friction ridge generalized position without disrupting the sequence of valid positions present in the image. This can help prompt an operator to recapture or record additional information about the subject.

In SlapSeg III, a number of images are missing fingers or otherwise have fingers that will not be able to be segmented. Reasons for segmentation failures reported by roc+0010 are enumerated in Table 30.

Failure Reason	Fingers
Finger Not Found	523
Finger Found, but Can't Segment	0
Vendor Defined	0

Table 30: Count of self-reported segmentation failure reasoning.

4.4.3 Identifying Missing Fingers

A small portion of the test corpus in SlapSeg III are missing fingers. Table 31 shows how successful roc+0010 was in correctly determining if a finger was missing. The *Missed* row shows when a segmentation position was returned for a missing finger. All possible failure reasons are enumerated, but are not considered *Correctly Identified* because the algorithm specified failure for a reason other than the finger not being found.

Result	Percentage
Missed	51.8
Correctly Identified	48.2
Other Failure: Finger Found, but Can't Segment	0.0
Other Failure: Vendor Defined	0.0
Other Failure: Segmentation Not Attempted	0.0

Table 31: Performance of roc+0010 at detecting fingers missing from an image.

4.4.4 Sequence Error

Sequence error occurs when a fingerprint is segmented from an image but assigned an incorrect finger position (e.g., segmenting a right middle finger but labeling it a right index finger). Table 32 shows cases in which a segmentation position was returned that matched a ground truth segmentation position for a different finger in the same image.

Table 32: Percentage of images in the dataset where one or more segmentation positions correctly matched an incorrect finger position within the same image, indicating sequence error.

Hand	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Left	7.03	7.03	7.29
Right	5.59	5.59	5.72
Combined	6.31	6.31	6.51

4.5 Determining Orientation

An *optional* portion of the SlapSeg III API asked participants to determine the hand orientation of an image. Participants were provided the kind (e.g., upper palm) and needed to determine whether the image was of the left or right hand.

Overall Upper Palm accuracy: 90.0%

Table 33: Percentage of accuracy when determining hand orientation of an upper palm image. The first column indicates the true hand orientation. Subsequent columns indicate the percentage of the time in which the indicated hand orientation was hypothesized.

	Left	Right	Skip
Left	88.9	7.1	4
Right	3.4	91	5.6

5 Full Palm ("EightInch" Data)

5.1 Segmentation Timing

All algorithms are run over a small fixed corpus of EightInch images to estimate the total runtime of the evaluation. To be evaluated under SlapSeg III, algorithms **must** segment the timing corpus, on average, in under 1 500 milliseconds. This maximum reference time is documented in the SlapSeg III test plan, and is subject to change. Times are measured by running a single process on an isolated compute node equipped with an Intel Gold 6254 CPU (submissions received prior to February 2022 were timed with a Intel Xeon E5-4650 CPU).

Box plots of segmentation times are separated by slap orientation in Figure 18. Tabular representations are enumerated in Table 34. Results are reported in milliseconds.

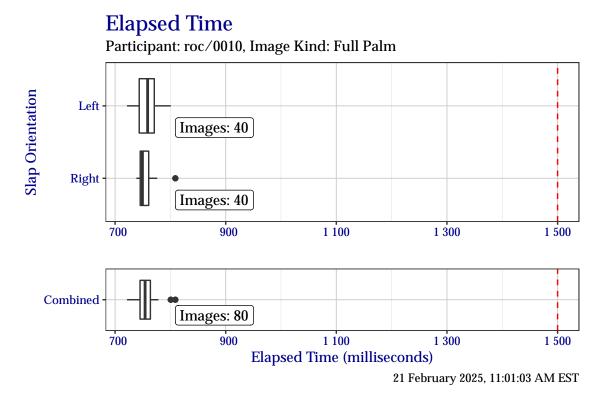


Figure 18: Box plots of elapsed time in milliseconds when segmenting the EightInch timing test corpus, separated by slap orientation.

Table 34: Elapsed time in milliseconds when segmenting the EightInch timing test corpus, separated by slap orientation and capture technology.

	Right	Left	Combined
Minimum	739	722	722
25%	745	744	745
Median	749	759	754
75%	761	771	764
Maximum	809	801	809

5.2 Segmentation Centers and Dimensions

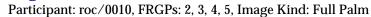
5.2.1 Segmentation Centers

The plots in this section show the distribution of segmentation position centers (x, y) for EightInch data. At the top of each figure is a combined plot for all finger positions of a given slap orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation centers for the right hand EightInch data are shown in Figure 19 and plots of segmentation centers for the left hand are shown in Figure 20. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Centers have been normalized to 500 pixels per inch.

Points in each plot are plotted with a semi-transparent opacity. This results in points of particular color appearing "darker" to indicate a higher frequency of the observed value, while "lighter" points indicate a lower observed frequency.

Segmentation Position Centers



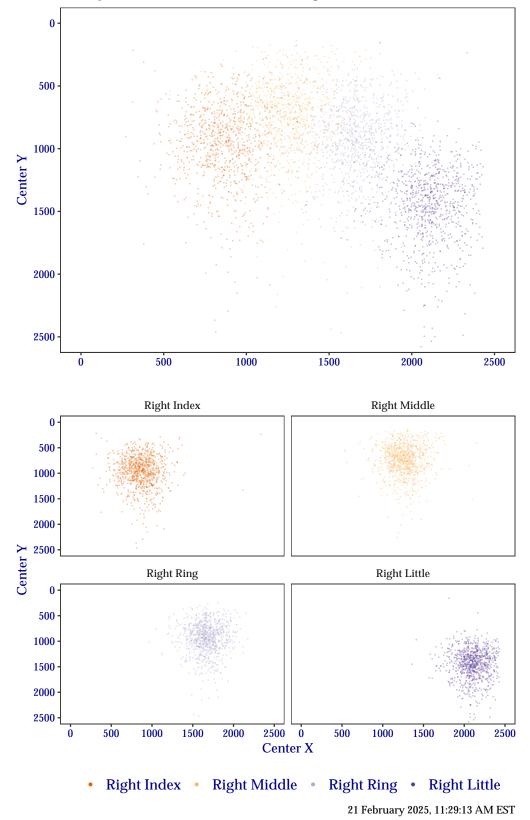
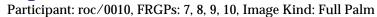


Figure 19: Segmentation centers for right hand EightInch data.

Segmentation Position Centers



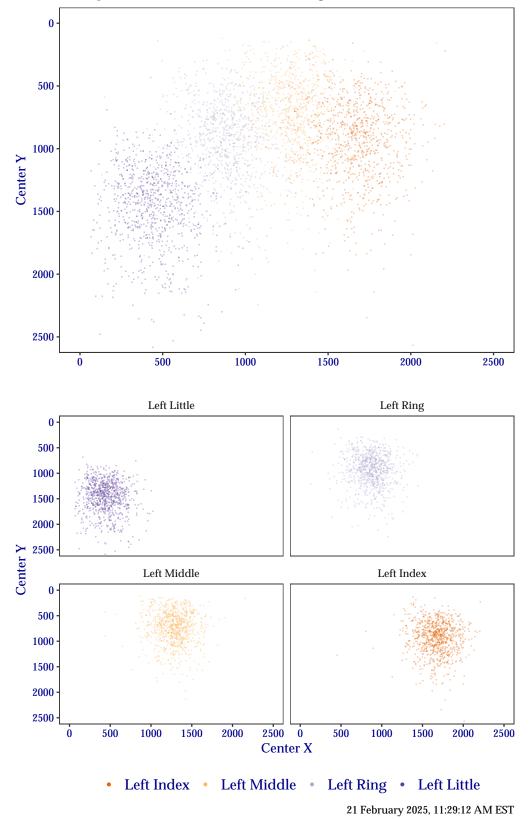


Figure 20: Segmentation centers for left hand EightInch data.

5.2.2 Segmentation Dimensions

The plots in this section show the distribution of segmentation position widths and heights for EightInch data. At the top of each figure is a combined plot for all finger positions of a given slap orientation. These figures are isolated in plots faceted at the bottom of the figure.

Plots of segmentation position dimensions for the right hand EightInch data are shown in Figure 21 and the left hand in Figure 22. Blank lines that may appear in the plots are **not** rendering artifacts. Rather, they are indicative of image downsampling. Dimensions have been normalized to 500 pixels per inch.

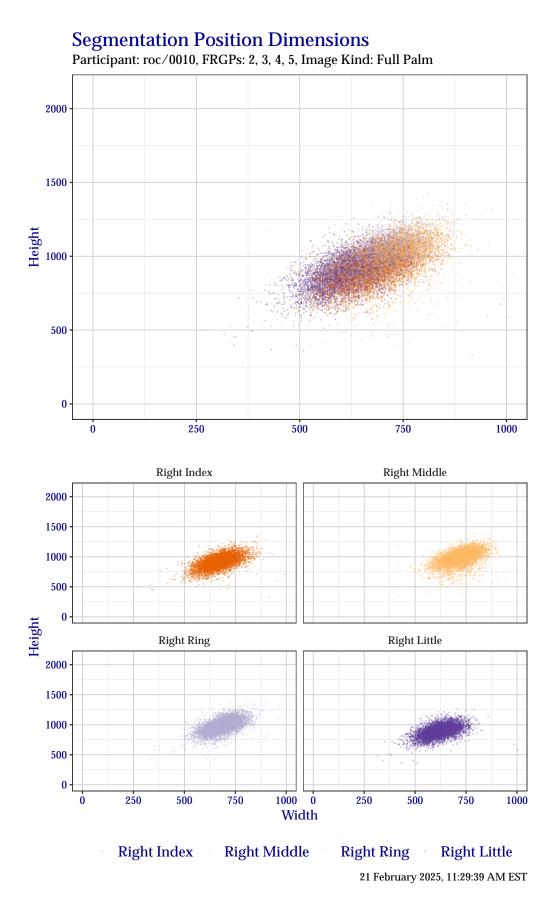


Figure 21: Segmentation position dimensions for right hand EightInch data.

0 •

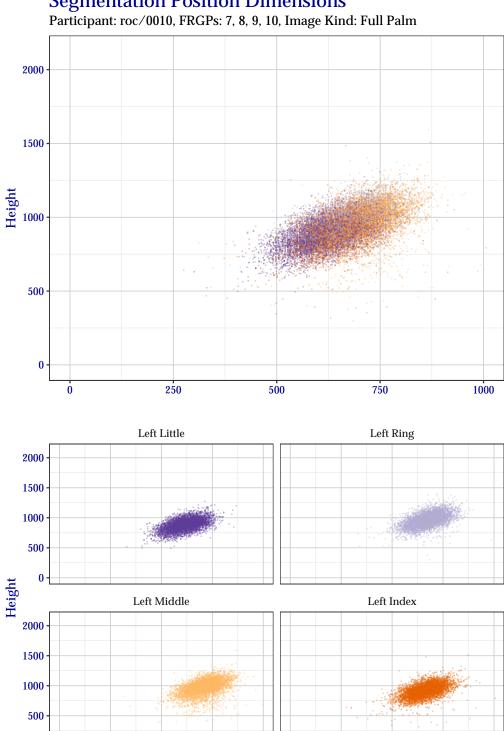
Ö

250

500

Left Index

750



Segmentation Position Dimensions

Figure 22: Segmentation position dimensions for left hand EightInch data.

Left Middle

1000 0

Width

250

Left Ring

500

750

Left Little

21 February 2025, 11:29:37 AM EST

1000

5.3 Detailed Segmentation Statistics

NOTE: *The following segmentation statistics are based on a limited subset (approximately 15%) of the anticipated Full Palm dataset. This analysis will be updated as soon as NIST can obtain the remainder of the dataset.*

This section shows detailed results of segmentation of EightInch data. Values in each table are the percentage that the variable in the left-most column was correctly segmented.

Each table has three columns of percentages. The *Standard Scoring* column shows the percentage of correctlysegmented positions based on the scoring metrics defined in the SlapSeg III scoring document. The *Ignoring Bottom Y* column shows how the percentage would change if the threshold for the *bottom Y* coordinate of the segmentation position was ignored. Similarly, the *Ignoring Bottom X and Y* columns shows how the percentage would change if only the top, left, and right sides of the segmentation position were considered. These two supplemental columns are included because it has traditionally been difficult to determine the exact location of the distal interphalangeal joint.

Table 35 shows how successful roc+0010 segmented fingers for each subject in the test corpus. Table 36 shows success for specific finger positions over the entire test corpus. Similarly, Table 37 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers on each slap image. Table 38 shows success for combinations of all fingers, Table 39 for just the index and middle fingers, and Table 40 for all except the little finger.

Table 35: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	100.0	100.0	100.0
2	100.0	100.0	100.0
3	100.0	100.0	100.0
4	99.7	99.7	99.7
5	99.2	99.2	99.2
6	97.9	98.4	98.5
7	96.2	96.4	96.7
8	88.2	88.9	89.7

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Index	97.1	97.5	97.8
Middle	96.9	96.9	96.9
Ring	97.6	98.0	98.0
Little	98.7	98.9	99.1
Left			
Index	97.6	97.7	97.8
Middle	97.6	97.6	97.6
Ring	97.4	97.7	98.0
Little	98.3	98.3	98.4

Table 36: For all subjects, percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Table 37: Percentage that a particular type of fingerprint was correctly segmented on *Either* or *Both* hands. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Index			
Either	99.9	99.9	99.9
Both	94.8	95.3	95.7
Middle			
Either	99.5	99.5	99.5
Both	94.9	94.9	94.9
Ring			
Either	99.5	99.7	99.7
Both	95.4	96.1	96.4
Little			
Either	100.0	100.0	100.0
Both	97.0	97.1	97.5

Table 38: Percentage of segmentation success by hand for combinations of all eight fingers of a EightInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and* Y only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	99.8	99.8	99.8
At Least Two	98.7	99.1	99.1
At Least Three	97.9	97.9	98.0
All Four	93.9	94.5	94.9
Left			
Any	99.9	99.9	99.9
At Least Two	99.3	99.4	99.4
At Least Three	98.4	98.5	98.7
All Four	93.2	93.4	93.8

Table 39: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	98.6	98.9	99.0
Both Index and Middle	95.4	95.5	95.7
Left			
Either Index or Middle	99.1	99.1	99.1
Both Index and Middle	96.1	96.2	96.3

Table 40: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Any	99.1	99.3	99.3
At Least Two	97.9	98.0	98.2
All Three	94.6	95.1	95.3
Left			
Any	99.3	99.4	99.4
At Least Two	98.6	98.7	98.9
All Three	94.6	94.8	95.2

5.4 Handling Troublesome Images

5.4.1 Capture Failures

Segmentation algorithms may refuse to process an image. This may happen for a technical reason (e.g., the algorithm cannot parse the image data), or for a practical reason (e.g., the hand in the image is placed incorrectly). These failure scenarios are the result of capturing improper image data. In these types of scenarios, it is important to examine the cause of the failure. With many live scan capture setups, segmentation is performed immediately after capture. If an algorithm can detect that it won't be able to segment an image due to a technical or practical issue, it can alert the operator to perform a recapture before the subject leaves.

The SlapSeg III API encourages algorithms to identify these failure reasons by specifying pre-defined *deficiencies* in the image. Algorithms should attempt segmentation even if an image deficiency is encountered if at all possible. Note that SlapSeg III *guarantees* well-formed image data, so failures to parse are **not** an indicator of the data provided.

roc+0010 did **not** report any capture failures.

5.4.1.1 Recovery

When encountering a segmentation failure, SlapSeg III algorithms are encouraged to provide a *best-effort* segmentation when possible. In some cases, that best-effort may be correct, which reduces the amount of images that need to be manually adjudicated by an operator.

roc+0010 did not attempt any recovery segmentations.

5.4.2 Segmentation Failures

Even if an algorithm accepts an image for processing, it can still fail to process one or more fingers from the image, regardless of if the algorithm requested a recapture and provided best-effort segmentation.

The SlapSeg III API allows algorithms to communicate reasons for failure to process these fingers. In some cases, the distal phalanx in question might not be present in the image due to amputation or being placed outside the platen's capture area. It is imperative that the segmentation algorithm correctly report this as failing to segment the correct friction ridge generalized position without disrupting the sequence of valid positions present in the image. This can help prompt an operator to recapture or record additional information about the subject.

In SlapSeg III, a number of images are missing fingers or otherwise have fingers that will not be able to be segmented. Reasons for segmentation failures reported by roc+0010 are enumerated in Table 41.

Failure Reason	Fingers
Finger Not Found	127
Finger Found, but Can't Segment	0
Vendor Defined	0

Table 41: Count of self-reported segmentation failure reasoning.

5.4.3 Identifying Missing Fingers

A small portion of the test corpus in SlapSeg III are missing fingers. Table 42 shows how successful roc+0010 was in correctly determining if a finger was missing. The *Missed* row shows when a segmentation position was returned for a missing finger. All possible failure reasons are enumerated, but are not considered *Correctly Identified* because the algorithm specified failure for a reason other than the finger not being found.

Result	Percentage
Missed	0.0
Correctly Identified	100.0
Other Failure: Finger Found, but Can't Segment	0.0
Other Failure: Vendor Defined	0.0
Other Failure: Segmentation Not Attempted	0.0

Table 42: Performance of roc+0010 at detecting fingers missing from an image.

5.4.4 Sequence Error

Sequence error occurs when a fingerprint is segmented from an image but assigned an incorrect finger position (e.g., segmenting a right middle finger but labeling it a right index finger). Table 43 shows cases in which a segmentation position was returned that matched a ground truth segmentation position for a different finger in the same image.

Table 43: Percentage of images in the dataset where one or more segmentation positions correctly matched an incorrect finger position within the same image, indicating sequence error.

Hand	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Left	0.92	0.92	0.92
Right	0.69	0.69	0.80
Combined	0.80	0.80	0.86

5.5 Determining Orientation

An *optional* portion of the SlapSeg III API asked participants to determine the hand orientation of an image. Participants were provided the kind (e.g., full palm) and needed to determine whether the image was of the left or right hand.

Overall Full Palm accuracy: 99.5%

Table 44: Percentage of accuracy when determining hand orientation of an full palm image. The first column indicates the true hand orientation. Subsequent columns indicate the percentage of the time in which the indicated hand orientation was hypothesized.

	Left	Right	Skip
Left	99.6	0.3	0.1
Right	0.5	99.5	0

A.1 Bootstrap Confidence for Segmentation Statistics

This section shows the same detailed results of segmentation of TwoInch data from Section 2.3, but with an added bootstrap confidence interval. For each observation, a bootstrap routine with 1 000 replicates was run, and a 95 % confidence interval extracted. The lower and upper confidence from that confidence interval are printed in each column within square brackets.

In Table 45, results are shown of how successful roc+0010 segmented fingers for each subject in the test corpus. Table 46 shows success for specific finger positions over the entire test corpus. Similarly, Table 47 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers in each slap image. Table 48 shows success for combinations of all fingers, Table 50 for the all except the little finger, and Table 49 for just the index and middle fingers.

Table 45: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	99.8 [99.7 <i>,</i> 99.9]	99.8 [99.7 <i>,</i> 99.9]	99.8 [99.8, 99.9]
2	99.7 [99.6, 99.8]	99.7 [99.6, 99.8]	99.8 [99.7 <i>,</i> 99.8]
3	99.5 [99.3, 99.6]	99.5 [99.4, 99.6]	99.6 [99.5 <i>,</i> 99.7]
4	98.8 [98.7, 99.0]	98.9 [98.7, 99.1]	99.0 [98.9 <i>,</i> 99.2]
5	95.1 [94.7, 95.4]	95.1 [94.7, 95.5]	95.2 [94.9 <i>,</i> 95.6]
6	94.6 [94.2, 95.0]	94.7 [94.3, 95.1]	95.0 [94.6, 95.3]
7	93.2 [92.7, 93.6]	93.6 [93.2, 94.0]	94.2 [93.8, 94.5]
8	82.9 [82.3, 83.6]	86.0 [85.4, 86.6]	87.7 [87.1, 88.3]

Table 46: For all subjects, Percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Index	96.2 [96.0, 96.5]	97.4 [97.2, 97.6]	98.4 [98.2, 98.5]
Middle	98.5 [98.3, 98.6]	98.9 [98.8, 99.0]	99.0 [98.9 <i>,</i> 99.2]
Ring	98.4 [98.2, 98.5]	98.7 [98.5, 98.8]	98.8 [98.7, 99.0]
Little	97.8 [97.6, 98.0]	98.4 [98.2, 98.5]	98.7 [98.5, 98.8]
Left			
Index	97.6 [97.4, 97.8]	98.0 [97.9, 98.2]	98.2 [98.1, 98.4]
Middle	97.9 [97.6, 98.1]	98.2 [98.0, 98.4]	98.4 [98.2, 98.5]
Ring	97.7 [97.5, 98.0]	98.2 [98.1, 98.4]	98.5 [98.4, 98.7]
Little	97.1 [96.9, 97.3]	97.3 [97.0, 97.5]	97.7 [97.6, 98.0]

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Index			
Either	99.3 [99.1, 99.4]	99.4 [99.2, 99.5]	99.5 [99.3 <i>,</i> 99.6]
Both	90.2 [89.6, 90.6]	91.5 [91.1, 92.0]	92.7 [92.2, 93.1]
Middle			
Either	99.5 [99.4, 99.6]	99.5 [99.4, 99.6]	99.6 [99.5 <i>,</i> 99.7]
Both	92.6 [92.2, 93.1]	93.3 [92.8, 93.8]	93.6 [93.2, 94.0]
Ring			
Either	99.4 [99.3, 99.5]	99.5 [99.4, 99.6]	99.6 [99.5 <i>,</i> 99.7]
Both	92.4 [91.9, 92.9]	93.2 [92.8, 93.7]	93.7 [93.2, 94.1]
Little			
Either	99.3 [99.1, 99.4]	99.3 [99.2, 99.4]	99.4 [99.3, 99.5]
Both	90.9 [90.3, 91.4]	91.6 [91.1, 92.0]	92.3 [91.8, 92.8]

Table 47: Percentage that a particular type of fingerprint was correctly segmented on *Either* or *Both* hands. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Table 48: Percentage of segmentation success by hand for combinations of all eight fingers of a TwoInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	99.7 [99.5, 99.7]	99.7 [99.6, 99.7]	99.7 [99.6, 99.7]
At Least Two	99.6 [99.3, 99.5]	99.6 [99.4, 99.5]	99.7 [99.5, 99.6]
At Least Three	99.1 [98.7, 98.9]	99.2 [98.9, 99.1]	99.5 [99.1, 99.3]
All Four	92.6 [92.5, 93.0]	94.8 [94.4, 94.8]	96.0 [95.3, 95.7]
Left			
Any	99.5 [99.5, 99.7]	99.5 [99.6, 99.7]	99.6 [99.6, 99.7]
At Least Two	99.2 [99.3, 99.5]	99.2 [99.4, 99.5]	99.4 [99.5, 99.6]
At Least Three	98.6 [98.7, 98.9]	98.7 [98.9 <i>,</i> 99.1]	99.0 [99.1, 99.3]
All Four	93.0 [92.5, 93.0]	94.4 [94.4, 94.8]	95.0 [95.3, 95.7]

Table 49: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	99.5 [99.3, 99.5]	99.5 [99.4, 99.5]	99.6 [99.4, 99.6]
Both Index and Middle	95.2 [95.5, 95.9]	96.8 [96.7, 97.0]	97.8 [97.4, 97.7]
Left			
Either Index or Middle	99.3 [99.3, 99.5]	99.3 [99.4, 99.5]	99.4 [99.4, 99.6]
Both Index and Middle	96.2 [95.5, 95.9]	96.9 [96.7, 97.0]	97.2 [97.4, 97.7]

Table 50: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	99.7 [99.5, 99.6]	99.7 [99.5 <i>,</i> 99.6]	99.7 [99.6, 99.7]
At Least Two	99.3 [99.0, 99.2]	99.4 [99.1, 99.3]	99.6 [99.3, 99.5]
All Three	94.1 [94.2, 94.7]	95.9 [95.8 <i>,</i> 96.1]	97.0 [96.5, 96.9]
Left			
Any	99.4 [99.5, 99.6]	99.4 [99.5, 99.6]	99.5 [99.6, 99.7]
At Least Two	98.9 [99.0, 99.2]	99.0 [99.1, 99.3]	99.2 [99.3, 99.5]
All Three	94.9 [94.2, 94.7]	96.0 [95.8, 96.1]	96.4 [96.5, 96.9]

A.2 Jaccard Index

Jaccard Similarity by Traditional Success Metric

Participant: roc/0010, Image Kind: Two Inch

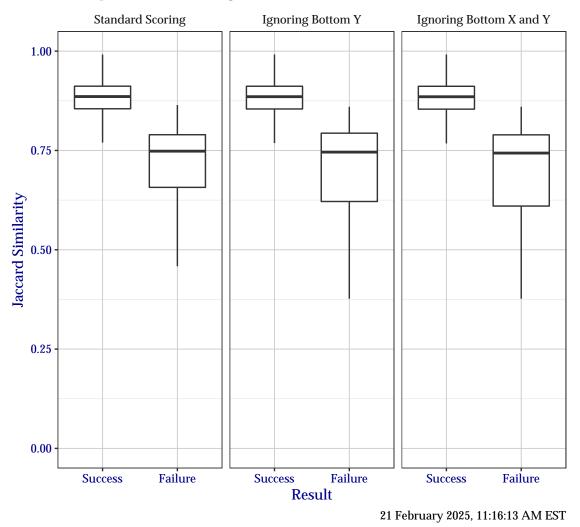


Figure 23: Boxplot of Jaccard similarity indices as compared to the traditional success metrics. Outliers have been removed for clarity.

Jaccard Similarity by Friction Ridge Generalized Position

Participant: roc/0010, Image Kind: Two Inch

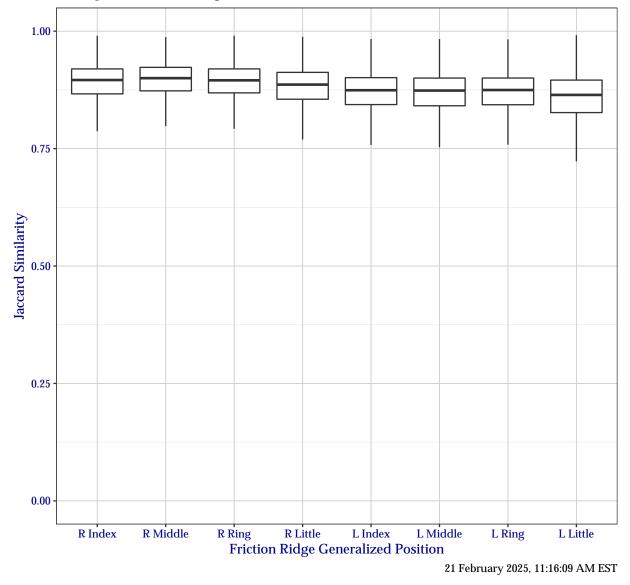


Figure 24: Boxplot of Jaccard similarity indices for each friction ridge generalized position. Outliers have been removed for clarity.

Number of Fingers	≥0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
1	100.0	100.0	99.9	99.8	87.5	16.8	0.3
2	100.0	100.0	99.9	99.7	72.1	3.4	0.0
3	99.9	99.9	99.8	99.4	51.8	0.6	0.0
4	99.7	99.7	99.5	98.2	30.4	0.1	0.0
5	95.9	95.9	95.8	94.2	15.0	0.0	0
6	95.9	95.9	95.7	91.8	6.7	0	0
7	95.8	95.7	95.0	83.8	2.3	0	0
8	94.1	92.6	87.8	59.1	0.5	0	0

Table 51: For each subject, the percentage that at least *Number of Fingers* fingers were segmented with a Jaccard index in the indicated range.

Table 52: For all subjects, percentage that a particular friction ridge generalized position was segmented with a Jaccard index in the indicated range.

Finger	0-0.5	0.5-0.6	0.6-0.7	0.7-0.8	0.8-0.9	0.9-1.0
Right						
Index	0.1	0.7	1.2	3.9	48.2	45.9
Middle	0.1	0.0	0.1	2.4	47.4	50.0
Ring	0.0	0.0	0.3	3.2	51.2	45.3
Little	0.4	0.2	0.7	5.3	56.6	36.8
Left						
Index	0.2	0.5	0.6	6.4	66.3	26.0
Middle	0.3	0.1	0.6	7.8	66.1	25.1
Ring	0.1	0.1	0.9	6.6	67.1	25.2
Little	0.8	0.1	0.8	11.6	64.8	21.9

Table 53: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of all eight fingers of a TwoInch slap.

Fingers	≥ 0.5	≥0.6	≥0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
Right							
Any	100.0	100.0	100.0	99.7	76.8	13.4	0.3
At Least Two	100.0	100.0	99.9	99.5	57.4	2.7	0.0
At Least Three	100.0	99.9	99.8	98.0	33.0	0.3	0.0
All Four	99.5	98.6	96.4	84.1	10.6	0.0	0.0
Left							
Any	100.0	100.0	99.9	99.2	50.6	4.4	0.1
At Least Two	99.9	99.9	99.9	97.8	29.9	0.6	0.0
At Least Three	99.9	99.9	99.6	92.9	14.0	0.1	0.0
All Four	98.8	98.0	95.5	72.6	3.7	0.0	0.0

Table 54: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index and middle fingers of a TwoInch slap.

Fingers	≥0.5	≥0.6	≥ 0.7	≥0.8	≥0.9	≥0.95	≥0.98
Right							
Either Index or Middle	100.0	100.0	99.9	99.5	66.1	8.5	0.1
Both Index and Middle	99.9	99.2	97.9	92.0	29.7	0.8	0.0
Left							
Either Index or Middle	99.9	99.9	99.8	97.7	38.5	2.6	0.0
Both Index and Middle	99.6	99.0	97.9	85.8	12.6	0.1	0.0

Table 55: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index, middle, and ring fingers of a TwoInch slap.

Fingers	≥0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
Right							
Āny	100.0	100.0	100.0	99.7	72.8	11.2	0.2
At Least Two	100.0	100.0	99.9	98.9	48.4	1.9	0.0
All Three	99.9	99.1	97.6	89.3	19.9	0.2	0.0
Left							
Any	100.0	100.0	99.9	98.8	45.8	3.5	0.1
At Least Two	99.9	99.9	99.7	95.5	23.1	0.4	0.0
All Three	99.5	98.9	97.1	81.6	7.4	0.1	0.0

B Identification Flats ("ThreeInch" Data)

B.1 Bootstrap Confidence for Segmentation Statistics

This section shows the same detailed results of segmentation of ThreeInch data from Section 3.3, but with an added bootstrap confidence interval. For each observation, a bootstrap routine with 1 000 replicates was run, and a 95 % confidence interval extracted. The lower and upper confidence from that confidence interval are printed in each column within square brackets.

In Table 56, results are shown of how successful roc+0010 segmented fingers for each subject in the test corpus. Table 57 shows success for specific finger positions over the entire test corpus. Similarly, Table 58 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers in each slap image. Table 59 shows success for combinations of all fingers, Table 61 for the all except the little finger, and Table 60 for just the index and middle fingers.

Table 56: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	99.9 [99.9, 100.0]	99.9 [99.9, 100.0]	99.9 [99.9, 100.0]
2	99.6 [99.6, 99.7]	99.6 [99.6, 99.7]	99.7 [99.6, 99.7]
3	98.5 [98.3, 98.6]	98.5 [98.3, 98.6]	98.5 [98.3, 98.6]
4	98.2 [98.0, 98.4]	98.2 [98.1, 98.4]	98.2 [98.1, 98.4]
	95.9 [95.7, 96.2]	95.9 [95.7, 96.2]	95.9 [95.7, 96.2]
6	95.9 [95.7, 96.2]	95.9 [95.7, 96.2]	95.9 [95.7 <i>,</i> 96.2]
7	95.8 [95.6, 96.1]	95.8 [95.6, 96.1]	95.9 [95.6, 96.1]
8	95.5 [95.2, 95.7]	95.5 [95.2, 95.7]	95.5 [95.3 <i>,</i> 95.8]
9	91.0 [90.7, 91.4]	91.2 [90.8, 91.5]	91.5 [91.1, 91.8]
10	79.1 [78.6, 79.6]	79.7 [79.1, 80.1]	81.1 [80.6, 81.6]

Table 57: For all subjects, Percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Thumb	90.3 [90.0, 90.7]	90.4 [90.1, 90.8]	90.9 [90.5, 91.2]
Index	99.6 [99.5, 99.7]	99.6 [99.5, 99.7]	99.7 [99.6, 99.7]
Middle	99.2 [99.1, 99.3]	99.3 [99.2, 99.4]	99.5 [99.4, 99.6]
Ring	98.2 [98.0, 98.3]	98.4 [98.2, 98.5]	98.5 [98.4, 98.7]
Little	98.0 [97.8, 98.2]	98.0 [97.8, 98.2]	98.1 [97.9 <i>,</i> 98.3]
Left			
Thumb	93.7 [93.4, 94.0]	93.8 [93.5, 94.1]	94.2 [93.9, 94.5]
Index	98.8 [98.7, 98.9]	98.8 [98.7, 98.9]	98.9 [98.7, 99.0]
Middle	99.3 [99.2, 99.4]	99.3 [99.2, 99.4]	99.5 [99.5, 99.6]
Ring	99.4 [99.3, 99.5]	99.5 [99.5 <i>,</i> 99.6]	99.7 [99.6, 99.8]
Little	99.4 [99.2, 99.4]	99.4 [99.3, 99.5]	99.4 [99.3, 99.5]

Table 58: Percentage that a particular type of fingerprint was correctly segmented on *Either* or *Both* hands. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Thumb			
Either	96.3 [96.0, 96.5]	96.3 [96.1, 96.6]	96.4 [96.1, 96.6]
Both	87.9 [87.4, 88.3]	88.1 [87.7, 88.5]	88.8 [88.4, 89.2]
Index			
Either	99.9 [99.8, 99.9]	99.9 [99.8 <i>,</i> 99.9]	99.9 [99.8, 99.9]
Both	95.8 [95.6, 96.1]	95.9 [95.6, 96.1]	96.0 [95.7, 96.2]
Middle			
Either	99.8 [99.8, 99.9]	99.8 [99.8 <i>,</i> 99.9]	99.9 [99.8 <i>,</i> 99.9]
Both	96.0 [95.7, 96.2]	96.0 [95.8, 96.3]	96.5 [96.3 <i>,</i> 96.7]
Ring			
Either	99.8 [99.8, 99.9]	99.9 [99.8 <i>,</i> 99.9]	99.9 [99.8, 99.9]
Both	95.0 [94.7, 95.3]	95.4 [95.1, 95.6]	95.7 [95.4 <i>,</i> 95.9]
Little			
Either	99.7 [99.6, 99.8]	99.7 [99.6, 99.8]	99.7 [99.7, 99.8]
Both	95.0 [94.7, 95.2]	95.0 [94.7, 95.2]	95.1 [94.9, 95.4]

Table 59: Percentage of segmentation success by hand for combinations of all ten fingers of a ThreeInch slap.
In <i>Ignoring Bottom Y</i> , the bottom left and bottom right Y coordinates are ignored. <i>Ignoring Bottom X and Y</i>
only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 %
confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Any	99.7 [99.7, 99.8]	99.7 [99.7 <i>,</i> 99.8]	99.7 [99.7, 99.8]
At Least Two	98.5 [98.4, 98.6]	98.5 [98.4, 98.6]	98.5 [98.4, 98.6]
At Least Three	98.4 [98.3, 98.5]	98.4 [98.3, 98.5]	98.4 [98.3, 98.5]
At Least Four	97.3 [97.5, 97.7]	97.4 [97.5, 97.8]	97.6 [97.6, 97.9]
All Five	82.5 [84.4, 85.0]	82.8 [84.7, 85.3]	83.7 [85.5, 86.1]
Left			
Any	99.8 [99.7 <i>,</i> 99.8]	99.8 [99.7 <i>,</i> 99.8]	99.9 [99.7 <i>,</i> 99.8]
At Least Two	98.5 [98.4, 98.6]	98.5 [98.4, 98.6]	98.5 [98.4, 98.6]
At Least Three	98.4 [98.3, 98.5]	98.4 [98.3, 98.5]	98.4 [98.3, 98.5]
At Least Four	97.8 [97.5, 97.7]	97.9 [97.5, 97.8]	98.0 [97.6, 97.9]
All Five	86.8 [84.4, 85.0]	87.1 [84.7, 85.3]	87.8 [85.5, 86.1]

Table 60: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	99.9 [99.9 <i>,</i> 99.9]	99.9 [99.9 <i>,</i> 99.9]	99.9 [99.9, 99.9]
Both Index and Middle	98.9 [98.4, 98.6]	99.0 [98.5, 98.7]	99.3 [98.8, 99.0]
Left			
Either Index or Middle	99.9 [99.9 <i>,</i> 99.9]	99.9 [99.9 <i>,</i> 99.9]	99.9 [99.9, 99.9]
Both Index and Middle	98.2 [98.4, 98.6]	98.2 [98.5, 98.7]	98.5 [98.8, 99.0]

Table 61: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y		
Right					
Any	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]		
At Least Two	99.7 [99.7 <i>,</i> 99.8]	99.7 [99.7 <i>,</i> 99.8]	99.8 [99.8, 99.8]		
All Three	97.3 [97.3, 97.6]	97.5 [97.6, 97.8]	98.0 [98.0, 98.3]		
Left					
Any	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]		
At Least Two	99.8 [99.7, 99.8]	99.8 [99.7, 99.8]	99.8 [99.8, 99.8]		
All Three	97.7 [97.3, 97.6]	97.9 [97.6, 97.8]	98.3 [98.0, 98.3]		

B.2 Jaccard Index

Jaccard Similarity by Traditional Success Metric

Participant: roc/0010, Image Kind: Three Inch

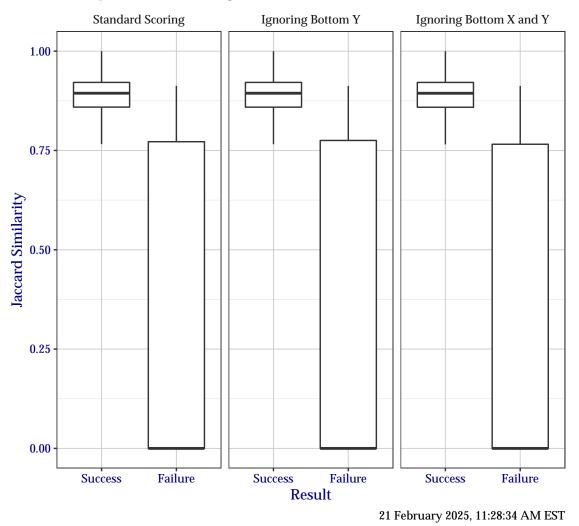


Figure 25: Boxplot of Jaccard similarity indices as compared to the traditional success metrics. Outliers have been removed for clarity.



1.00 0.75 Jaccard Similarity 0.50 0.25 0.00 R Little L Thumb L Index L Middle R Thumb **R** Index R Middle R Ring L Ring L Little Friction Ridge Generalized Position

21 February 2025, 11:28:29 AM EST

Figure 26: Boxplot of Jaccard similarity indices for each friction ridge generalized position. Outliers have been removed for clarity.

Number of Fingers	≥0.5	≥0.6	≥0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
1	100.0	100.0	100.0	99.9	97.6	41.5	2.1
2	99.9	99.9	99.9	99.5	92.1	11.6	0.0
3	98.5	98.5	98.5	98.0	82.4	2.5	0.0
4	98.4	98.3	98.2	97.2	66.0	0.4	0.0
5	95.9	95.9	95.9	95.8	45.9	0.1	0.0
6	95.9	95.9	95.9	95.5	26.0	0.0	0
7	95.9	95.9	95.9	94.0	11.5	0	0
8	95.8	95.8	95.6	89.9	3.5	0	0
9	92.6	92.6	91.9	77.0	0.7	0	0
10	87.7	87.4	83.8	48.3	0.1	0	0

Table 62: For each subject, the percentage that at least *Number of Fingers* fingers were segmented with a Jaccard index in the indicated range.

Table 63: For all subjects, percentage that a particular friction ridge generalized position was segmented with
a Jaccard index in the indicated range.

Finger	0-0.5	0.5-0.6	0.6-0.7	0.7-0.8	0.8-0.9	0.9-1.0
Right						
Thumb	7.2	0.0	0.3	6.3	40.4	45.8
Index	0.1	0.0	0.4	3.5	43.4	52.6
Middle	0.1	0.0	0.3	3.0	39.4	57.2
Ring	0.1	0.0	0.5	3.9	41.3	54.2
Little	0.7	0.1	0.5	7.6	53.5	37.6
Left						
Thumb	3.9	0.2	1.3	13.2	52.4	29.0
Index	0.1	0.0	0.2	2.5	42.1	55.1
Middle	0.1	0.0	0.2	3.2	49.0	47.5
Ring	0.2	0.0	0.5	6.1	60.2	33.0
Little	0.1	0.1	0.8	13.6	61.6	23.8

Table 64: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of all ten fingers of a ThreeInch slap.

Fingers	≥ 0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
Right							
Any	99.9	99.9	99.9	99.7	92.4	29.2	1.5
At Least Two	98.5	98.5	98.5	98.0	74.9	5.8	0.0
At Least Three	98.5	98.5	98.4	96.6	48.9	0.8	0.0
At Least Four	98.3	98.3	97.9	92.6	22.2	0.1	0.0
All Five	87.6	87.5	86.0	70.1	4.7	0.0	0.0
Left							
Any	99.9	99.9	99.9	99.7	87.2	18.1	0.7
At Least Two	98.5	98.5	98.5	98.0	59.7	2.1	0.0
At Least Three	98.5	98.5	98.4	96.6	28.8	0.2	0.0
At Least Four	98.3	98.3	97.9	90.1	8.4	0.0	0.0
All Five	91.1	90.8	88.4	61.1	1.1	0.0	0.0

Table 65: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for	r
combinations of index and middle fingers of a ThreeInch slap.	

Fingers	≥0.5	≥0.6	≥0.7	≥0.8	≥0.9	≥0.95	≥0.98
Right							
Either Index or Middle	99.9	99.9	99.9	98.7	76.0	13.4	0.5
Both Index and Middle	99.8	99.8	99.2	93.8	33.8	1.1	0.0
Left							
Either Index or Middle	99.9	99.9	99.9	99.2	72.3	11.0	0.3
Both Index and Middle	99.8	99.8	99.4	94.4	30.3	0.7	0

Table 66: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index, middle, and ring fingers of a ThreeInch slap.

-							
Fingers	≥0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
Right							
Āny	100.0	100.0	100.0	99.4	84.7	19.2	0.9
At Least Two	99.9	99.9	99.7	97.6	57.0	3.0	0.0
All Three	99.8	99.7	98.7	91.1	22.3	0.2	0.0
Left							
Any	100.0	100.0	100.0	99.6	79.5	13.0	0.4
At Least Two	99.9	99.9	99.8	98.1	44.4	1.1	0.0
All Three	99.7	99.6	98.8	89.2	11.7	0.1	0

C Upper Palm ("FiveInch" Data)

C.1 Bootstrap Confidence for Segmentation Statistics

This section shows the same detailed results of segmentation of FiveInch data from Section 4.3, but with an added bootstrap confidence interval. For each observation, a bootstrap routine with 1 000 replicates was run, and a 95 % confidence interval extracted. The lower and upper confidence from that confidence interval are printed in each column within square brackets.

In Table 67, results are shown of how successful roc+0010 segmented fingers for each subject in the test corpus. Table 68 shows success for specific finger positions over the entire test corpus. Similarly, Table 69 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers in each slap image. Table 70 shows success for combinations of all fingers, Table 72 for the all except the little finger, and Table 71 for just the index and middle fingers.

Table 67: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	99.9 [99.6, 100.0]	99.9 [99.6, 100.0]	99.9 [99.6, 100.0]
2	98.9 [98.2, 99.6]	99.1 [98.3, 99.7]	99.1 [98.3 <i>,</i> 99.7]
3	97.2 [96.0, 98.3]	97.4 [96.2, 98.4]	97.4 [96.1, 98.4]
4	94.3 [92.8, 95.9]	94.3 [92.8, 95.9]	94.3 [92.6, 95.9]
5	89.3 [87.1, 91.6]	89.5 [87.2, 91.6]	89.6 [87.5, 91.8]
6	82.6 [79.8, 85.4]	82.9 [80.1, 85.6]	83.0 [80.2, 85.6]
7	73.6 [70.6, 76.8]	73.6 [70.2, 76.7]	74.2 [71.1, 77.5]
8	58.8 [55.5, 62.1]	59.3 [55.6, 62.8]	60.5 [57.0, 63.9]

Table 68: For all subjects, Percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Index	88.3 [85.9, 90.6]	88.3 [86.0, 90.6]	88.6 [86.2, 90.8]
Middle	85.8 [83.2, 88.2]	86.2 [83.6, 88.6]	86.6 [83.9, 89.0]
Ring	89.8 [87.6, 91.9]	90.2 [87.8, 92.4]	90.2 [88.2, 92.3]
Little	91.9 [89.9, 93.9]	91.9 [89.8, 93.8]	91.9 [90.0, 93.8]
Left			
Index	86.6 [84.0, 89.0]	86.7 [84.2, 89.3]	87.0 [84.5, 89.4]
Middle	85.3 [82.9, 87.8]	85.4 [82.9, 87.8]	85.4 [82.8, 88.1]
Ring	85.9 [83.4, 88.6]	86.1 [83.8, 88.6]	86.6 [84.0, 89.0]
Little	86.7 [84.2, 89.1]	86.7 [84.5, 89.0]	87.3 [84.9, 89.5]

Table 69: Percentage that a particular type of fingerprint was correctly segmented on <i>Either</i> or <i>Both</i> hands. In
Ignoring Bottom Y, the bottom left and bottom right Y coordinates are ignored. Ignoring Bottom X and Y only
checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 %
confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Index			
Either	94.6 [93.0, 96.2]	94.6 [92.9, 96.0]	94.6 [93.0, 96.0]
Both	78.9 [75.8, 81.8]	79.1 [76.2, 81.8]	79.6 [76.8, 82.3]
Middle			
Either	94.5 [92.6, 96.0]	94.9 [93.3, 96.3]	95.0 [93.3, 96.6]
Both	75.2 [71.9, 78.4]	75.4 [72.5, 78.4]	75.6 [72.6, 78.4]
Ring			
Either	95.7 [94.2, 97.0]	95.8 [94.5 <i>,</i> 97.2]	95.8 [94.3, 97.1]
Both	78.7 [75.9, 81.4]	79.1 [76.2, 81.9]	79.6 [76.9, 82.2]
Little			
Either	97.6 [96.6, 98.7]	97.6 [96.4, 98.7]	97.8 [96.7, 98.7]
Both	79.6 [76.7, 82.3]	79.6 [76.6, 82.3]	80.0 [76.9, 82.9]

Table 70: Percentage of segmentation success by hand for combinations of all eight fingers of a FiveInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	98.5 [97.9, 99.1]	98.5 [97.9 <i>,</i> 99.1]	98.5 [97.9, 99.1]
At Least Two	94.0 [92.2, 94.8]	94.1 [92.4, 94.8]	94.1 [92.4, 94.8]
At Least Three	86.7 [82.9, 86.5]	87.0 [83.3, 86.8]	87.0 [83.5, 87.0]
All Four	76.5 [70.9, 75.4]	76.9 [71.3, 75.8]	77.5 [72.0, 76.3]
Left			
Any	98.5 [97.9, 99.1]	98.5 [97.9 <i>,</i> 99.1]	98.7 [97.9, 99.1]
At Least Two	93.1 [92.2, 94.8]	93.1 [92.4, 94.8]	93.1 [92.4, 94.8]
At Least Three	83.0 [82.9, 86.5]	83.2 [83.3, 86.8]	83.6 [83.5, 87.0]
All Four	69.9 [70.9, 75.4]	70.2 [71.3, 75.8]	71.0 [72.0, 76.3]

Table 71: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	93.2 [92.0, 94.6]	93.4 [92.3, 94.7]	93.4 [92.2, 94.8]
Both Index and Middle	80.9 [77.6, 81.5]	81.1 [77.9, 81.9]	81.8 [78.0, 82.2]
Left			
Either Index or Middle	93.5 [92.0, 94.6]	93.6 [92.3, 94.7]	93.8 [92.2, 94.8]
Both Index and Middle	78.4 [77.6, 81.5]	78.5 [77.9, 81.9]	78.6 [78.0, 82.2]

Table 72: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	96.4 [95.2, 97.1]	96.5 [95.4, 97.2]	96.5 [95.4, 97.3]
At Least Two	89.2 [86.3, 89.4]	89.5 [86.4, 89.8]	89.5 [86.5, 89.7]
All Three	78.2 [74.6, 78.7]	78.6 [74.9, 79.2]	79.3 [75.3, 79.7]
Left			
Any	96.0 [95.2, 97.1]	96.0 [95.4, 97.2]	96.2 [95.4, 97.3]
At Least Two	86.6 [86.3, 89.4]	86.7 [86.4, 89.8]	86.9 [86.5, 89.7]
All Three	75.2 [74.6, 78.7]	75.5 [74.9, 79.2]	76.0 [75.3, 79.7]

C.2 Jaccard Index

Jaccard Similarity by Traditional Success Metric

Participant: roc/0010, Image Kind: Upper Palm

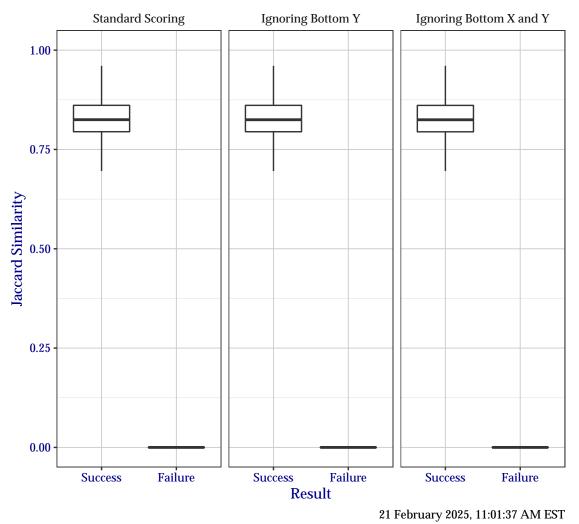
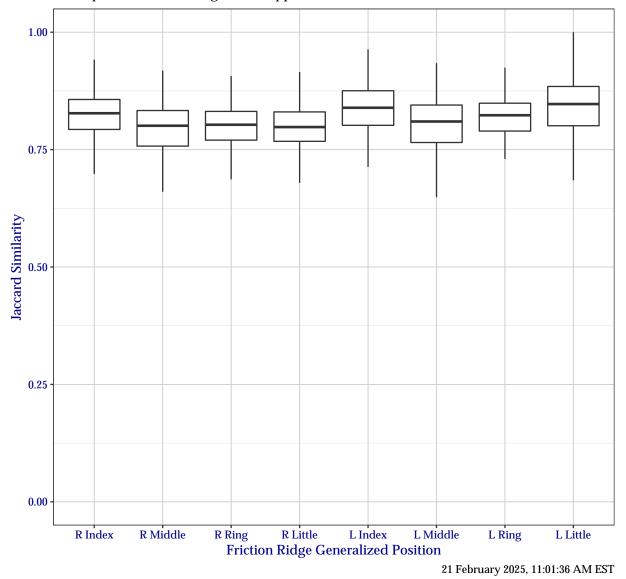


Figure 27: Boxplot of Jaccard similarity indices as compared to the traditional success metrics. Outliers have been removed for clarity.

Jaccard Similarity by Friction Ridge Generalized Position



Participant: roc/0010, Image Kind: Upper Palm

Figure 28: Boxplot of Jaccard similarity indices for each friction ridge generalized position. Outliers have been removed for clarity.

Number of Fingers	≥0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95	≥0.98
1	100.0	100.0	99.9	99.2	40.8	20.0	19.0
2	99.2	99.1	99.1	96.7	16.7	12.6	12.6
3	97.6	97.6	97.4	91.7	9.7	8.6	8.6
4	94.5	94.3	93.5	81.9	7.5	7.1	7.1
5	89.5	89.3	88.9	62.3	4.9	4.3	4.3
6	83.9	83.5	81.7	39.1	3.0	2.9	2.9
7	75.6	75.4	73.5	19.6	2.6	2.6	2.6
8	68.2	67.3	63.0	5.1	1.3	1.3	1.3

Table 73: For each subject, the percentage that at least *Number of Fingers* fingers were segmented with a Jaccard index in the indicated range.

Table 74: For all subjects, percentage that a particular friction ridge generalized position was segmented with a Jaccard index in the indicated range.

Finger	0-0.5	0.5-0.6	0.6-0.7	0.7-0.8	0.8-0.9	0.9-1.0
Right						
Index	10.8	0.3	1.5	16.7	62.5	8.2
Middle	12.9	0.4	1.7	33.9	40.3	10.8
Ring	9.6	0.3	1.6	35.6	42.7	10.2
Little	6.8	0.1	1.2	43.5	40.8	7.6
Left						
Index	12.5	0	0.2	11.8	61.7	13.8
Middle	14.2	0.5	1.7	27.1	45.8	10.7
Ring	12.2	0.4	0.5	17.6	59.7	9.6
Little	6.9	0	1.2	16.6	58.9	16.4

Table 75: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of all ten fingers of a FiveInch slap.

Fingers	≥ 0.5	≥0.6	≥0.7	≥0.8	≥0.9	≥0.95	≥0.98
Right							
Any	98.7	98.7	98.5	91.8	18.8	14.9	14.8
At Least Two	94.3	94.1	93.8	75.3	9.0	8.8	8.8
At Least Three	87.0	86.7	85.6	43.4	5.7	5.6	5.6
All Four	80.1	79.4	75.0	12.8	3.3	3.2	3.2
Left							
Any	99.1	98.9	98.8	96.9	34.0	13.9	13.0
At Least Two	93.9	93.8	93.4	86.3	9.8	7.3	7.3
At Least Three	84.4	84.4	83.7	65.0	4.4	4.1	4.1
All Four	76.9	76.3	73.7	28.2	2.4	2.3	2.3

Table 76: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index and middle fingers of a FiveInch slap.

Fingers	≥0.5	≥0.6	≥0.7	≥0.8	≥0.9	≥0.95	≥0.98
Right							
Either Index or Middle	93.6	93.4	92.8	83.5	14.5	11.6	11.6
Both Index and Middle	82.7	82.3	79.7	38.3	4.5	4.3	4.3
Left							
Either Index or Middle	93.9	93.9	93.5	87.4	21.4	11.4	11.0
Both Index and Middle	79.4	78.9	77.3	44.6	3.2	2.9	2.9

Table 77: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index, middle, and ring fingers of a FiveInch slap.

Fingers	≥0.5	≥0.6	≥0.7	≥0.8	≥0.9	≥0.95	≥0.98
Right							
Āny	96.7	96.5	96.1	88.6	17.3	14.1	14.1
At Least Two	89.4	89.1	88.4	64.6	8.1	7.8	7.8
All Three	80.7	80.2	76.5	21.5	3.9	3.7	3.7
Left							
Any	96.3	96.2	95.9	92.2	24.0	13.1	12.7
At Least Two	87.3	87.1	86.7	74.3	7.4	6.9	6.9
All Three	77.6	76.9	75.1	34.7	2.7	2.7	2.7

D Full Palm ("EightInch" Data)

D.1 Bootstrap Confidence for Segmentation Statistics

NOTE: *The following segmentation statistics are based on a limited subset (approximately 15%) of the anticipated Full Palm dataset. This analysis will be updated as soon as NIST can obtain the remainder of the dataset.*

This section shows the same detailed results of segmentation of EightInch data from Section 5.3, but with an added bootstrap confidence interval. For each observation, a bootstrap routine with 1 000 replicates was run, and a 95 % confidence interval extracted. The lower and upper confidence from that confidence interval are printed in each column within square brackets.

In Table 78, results are shown of how successful roc+0010 segmented fingers for each subject in the test corpus. Table 79 shows success for specific finger positions over the entire test corpus. Similarly, Table 80 shows success for segmenting the same finger position from both hands.

The remainder of the tables show success per subject when considering combinations of subsets of the fingers in each slap image. Table 81 shows success for combinations of all fingers, Table 83 for the all except the little finger, and Table 82 for just the index and middle fingers.

Table 78: For each subject, the percentage that at least *Number of Fingers* fingers were correctly segmented, regardless of hand, for a maximum of eight correctly-segmented fingers. In *Standard Scoring*, scoring rules are followed exactly. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Number of Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
1	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]
2	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]
3	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]
4	99.7 [99.2, 100.0]	99.7 [99.3, 100.0]	99.7 [99.2, 100.0]
5	99.2 [98.6, 99.8]	99.2 [98.6, 99.8]	99.2 [98.6, 99.8]
6	97.9 [96.9, 98.9]	98.4 [97.6, 99.2]	98.5 [97.7 <i>,</i> 99.2]
7	96.2 [94.8, 97.4]	96.4 [95.2, 97.6]	96.7 [95.4, 97.7]
8	88.2 [86.0, 90.3]	88.9 [86.8, 90.9]	89.7 [87.5, 91.7]

Table 79: For all subjects, Percentage that a particular friction ridge generalized position was correctly segmented. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Finger	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Index	97.1 [96.0, 98.2]	97.5 [96.3, 98.5]	97.8 [96.8, 98.7]
Middle	96.9 [95.6, 97.9]	96.9 [95.7, 98.0]	96.9 [95.6, 98.0]
Ring	97.6 [96.6, 98.6]	98.0 [97.0 <i>,</i> 98.9]	98.0 [97.1, 99.0]
Little	98.7 [97.9, 99.4]	98.9 [98.0 <i>,</i> 99.5]	99.1 [98.4, 99.7]
Left			
Index	97.6 [96.4, 98.5]	97.7 [96.7, 98.7]	97.8 [96.7, 98.7]
Middle	97.6 [96.6, 98.6]	97.6 [96.6, 98.6]	97.6 [96.6, 98.6]
Ring	97.4 [96.3, 98.4]	97.7 [96.7, 98.6]	98.0 [97.0, 98.9]
Little	98.3 [97.4, 99.1]	98.3 [97.4, 99.1]	98.4 [97.6, 99.2]

Table 80: Percentage that a particular type of fingerprint was correctly segmented on <i>Either</i> or <i>Both</i> hands. In
Ignoring Bottom Y, the bottom left and bottom right Y coordinates are ignored. Ignoring Bottom X and Y only
checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 %
confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Index			
Either	99.9 [99.7, 100.0]	99.9 [99.7, 100.0]	99.9 [99.7 <i>,</i> 100.0]
Both	94.8 [93.3, 96.2]	95.3 [93.8, 96.6]	95.7 [94.4, 97.0]
Middle			
Either	99.5 [99.1, 99.9]	99.5 [99.1, 99.9]	99.5 [99.0, 99.9]
Both	94.9 [93.3, 96.4]	94.9 [93.4, 96.3]	94.9 [93.4, 96.3]
Ring			
Either	99.5 [99.1, 99.9]	99.7 [99.2, 100.0]	99.7 [99.2 <i>,</i> 100.0]
Both	95.4 [93.9, 96.7]	96.1 [94.8, 97.4]	96.4 [95.2 <i>,</i> 97.7]
Little			
Either	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]	100.0 [100.0, 100.0]
Both	97.0 [96.0, 98.0]	97.1 [96.0, 98.2]	97.5 [96.3, 98.5]

Table 81: Percentage of segmentation success by hand for combinations of all eight fingers of a EightInch slap. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and* Y only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	99.8 [99.6, 100.0]	99.8 [99.6, 100.0]	99.8 [99.6, 100.0]
At Least Two	98.7 [98.5, 99.5]	99.1 [98.8, 99.7]	99.1 [98.8, 99.7]
At Least Three	97.9 [97.5, 98.8]	97.9 [97.6, 98.8]	98.0 [97.7, 99.0]
All Four	93.9 [92.4, 94.7]	94.5 [92.9, 95.1]	94.9 [93.3, 95.5]
Left			
Any	99.9 [99.6, 100.0]	99.9 [99.6, 100.0]	99.9 [99.6, 100.0]
At Least Two	99.3 [98.5, 99.5]	99.4 [98.8, 99.7]	99.4 [98.8, 99.7]
At Least Three	98.4 [97.5, 98.8]	98.5 [97.6, 98.8]	98.7 [97.7, 99.0]
All Four	93.2 [92.4, 94.7]	93.4 [92.9, 95.1]	93.8 [93.3, 95.5]

Table 82: Percentage of segmentation success by hand when only considering combinations of index and middle fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95% confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Either Index or Middle	98.6 [98.3, 99.3]	98.9 [98.4, 99.4]	99.0 [98.5, 99.4]
Both Index and Middle	95.4 [94.8, 96.7]	95.5 [95.0 <i>,</i> 96.8]	95.7 [95.1, 96.9]
Left			
Either Index or Middle	99.1 [98.3, 99.3]	99.1 [98.4, 99.4]	99.1 [98.5 <i>,</i> 99.4]
Both Index and Middle	96.1 [94.8, 96.7]	96.2 [95.0, 96.8]	96.3 [95.1, 96.9]

Table 83: Percentage of segmentation success by hand when only considering combinations of index, middle, and ring fingers. In *Ignoring Bottom Y*, the bottom left and bottom right Y coordinates are ignored. *Ignoring Bottom X and Y* only checks the locations of the top left and top right coordinates. Values in square brackets represent a 95 % confidence interval after bootstrapping with 1 000 replicates.

Fingers	Standard Scoring	Ignoring Bottom Y	Ignoring Bottom X and Y
Right			
Āny	99.1 [98.8, 99.6]	99.3 [99.0, 99.7]	99.3 [99.0, 99.7]
At Least Two	97.9 [97.6, 98.9]	98.0 [97.8 <i>,</i> 99.0]	98.2 [97.9, 99.1]
All Three	94.6 [93.6, 95.7]	95.1 [93.9 <i>,</i> 96.0]	95.3 [94.3, 96.2]
Left			
Any	99.3 [98.8, 99.6]	99.4 [99.0 <i>,</i> 99.7]	99.4 [99.0, 99.7]
At Least Two	98.6 [97.6, 98.9]	98.7 [97.8 <i>,</i> 99.0]	98.9 [97.9, 99.1]
All Three	94.6 [93.6, 95.7]	94.8 [93.9, 96.0]	95.2 [94.3, 96.2]

D.2 Jaccard Index

Jaccard Similarity by Traditional Success Metric

Participant: roc/0010, Image Kind: Full Palm

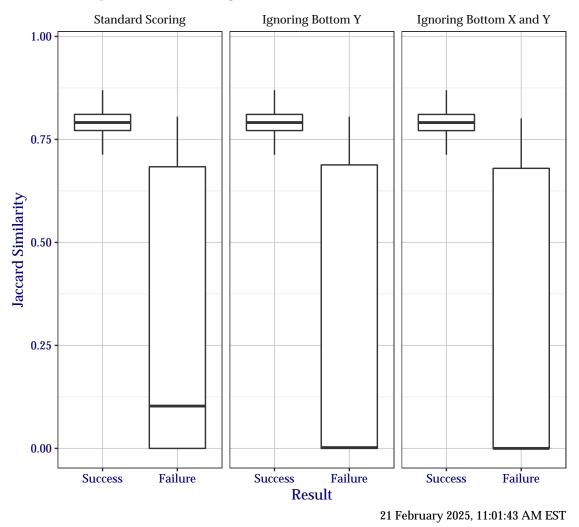


Figure 29: Boxplot of Jaccard similarity indices as compared to the traditional success metrics. Outliers have been removed for clarity.

Jaccard Similarity by Friction Ridge Generalized Position

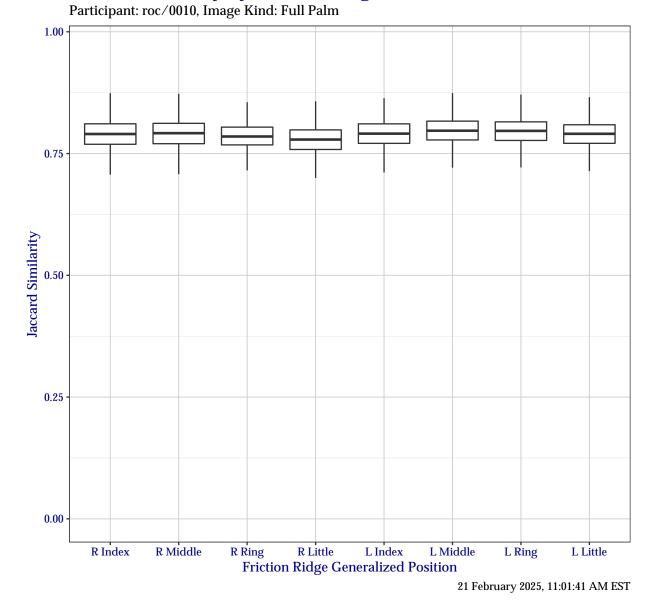


Figure 30: Boxplot of Jaccard similarity indices for each friction ridge generalized position. Outliers have been removed for clarity.

Number of Fingers	≥0.5	≥0.6	≥0.7	≥0.8	≥0.9	≥0.95
1	100.0	100.0	100.0	91.6	3.7	0.2
2	100.0	100.0	100.0	76.4	1.3	0
3	100.0	100.0	99.8	54.4	0.3	0
4	99.8	99.7	99.5	33.2	0	0
5	99.4	99.4	99.0	18.5	0	0
6	98.3	98.3	97.5	10.5	0	0
7	97.4	97.2	94.4	5.7	0	0
8	94.9	93.9	83.7	2.9	0	0

Table 84: For each subject, the percentage that at least *Number of Fingers* fingers were segmented with a Jaccard index in the indicated range.

Table 85: For all subjects, percentage that a particular friction ridge generalized position was segmented with a Jaccard index in the indicated range.

Finger	0-0.5	0.5-0.6	0.6-0.7	0.7-0.8	0.8-0.9	0.9-1.0
Right						
Index	2.1	0	1.8	58.4	37.2	0.5
Middle	1.6	0.2	2.3	55.4	40.0	0.5
Ring	1.4	0.2	2.2	66.2	29.1	0.9
Little	0.8	0.1	1.5	73.9	23.7	0
Left						
Index	1.6	0.2	1.9	58.3	36.7	1.3
Middle	1.4	0	1.7	52.3	44.0	0.6
Ring	1.3	0.2	1.4	53.1	43.3	0.7
Little	0.1	0.2	1.9	63.0	33.9	0.9

Table 86: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of all ten fingers of a EightInch slap.

Fingers	≥ 0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95
Right						
Any	99.9	99.8	99.7	73.1	1.4	0.2
At Least Two	99.0	99.0	98.6	37.6	0.3	0.0
At Least Three	98.3	98.3	96.9	15.1	0.1	0.0
All Four	97.0	96.6	90.6	6.1	0.0	0.0
Left						
Any	99.9	99.9	99.8	77.8	2.6	0.0
At Least Two	99.3	99.3	99.3	50.8	0.7	0.0
At Least Three	99.0	99.0	97.7	23.6	0.1	0.0
All Four	97.5	96.8	91.3	9.2	0.0	0.0

Fingers	≥ 0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95
Right						
Either Index or Middle	98.9	98.7	98.4	58.4	0.8	0.2
Both Index and Middle	97.5	97.4	93.6	19.8	0.1	0
Left						
Either Index or Middle	99.1	99.1	99.0	60.3	1.7	0
Both Index and Middle	97.9	97.7	94.1	22.2	0.1	0

Table 87: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index and middle fingers of a EightInch slap.

Table 88: Percentage of segmentation obtaining a Jaccard index in the indicated ranges, by hand, for combinations of index, middle, and ring fingers of a EightInch slap.

-						
Fingers	≥0.5	≥0.6	≥ 0.7	≥ 0.8	≥0.9	≥0.95
Right						
Āny	99.4	99.3	99.1	68.2	1.4	0.2
At Least Two	98.3	98.3	97.2	30.2	0.3	0
All Three	97.2	96.9	91.8	9.8	0.1	0
Left						
Any	99.3	99.3	99.3	72.3	2.2	0
At Least Two	99.0	99.0	98.3	40.1	0.3	0
All Three	97.5	97.0	92.6	14.1	0	0